# On the convergence of Boolean automata networks without negative cycles

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Convergence of Boolean networks without negative cycles

#### **Boolean networks**

#### Finite and heterogeneous CAs on $\{0, 1\}$

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#### **Boolean networks**

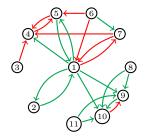
Finite and heterogeneous CAs on  $\{0, 1\}$ 

Classical models for

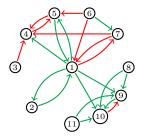
Neural networks [McCulloch & Pitts 1943] Gene regulatory networks [Kauffman 1969, Tomas 1973]

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#### Focus on interaction graphs



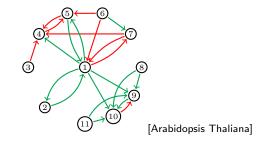
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#### Question

What can be said on the dynamics of a Boolean network according to its interaction graph  $? \end{tabular}$ 

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What can be said on the dynamics of a Boolean network according to its interaction graph ?

## Application to **gene networks**: reliable information on the interaction graph only.

### Definitions

#### Setting

There are n components (cells) denoted from 1 to nThe set of possible states (configurations) is  $\{0,1\}^n$ The local transition function of component  $i \in [n]$  is any map

 $f_i: \{0,1\}^n \to \{0,1\}$ 

The resulting global transition function is

 $f: \{0,1\}^n \to \{0,1\}^n, \qquad f(x) = (f_1(x), \dots, f_n(x))$ 

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## We consider the **fully-asynchronous** updating $\hookrightarrow$ very usual in the context of **gene networks** [Thomas 73]

Given a map  $v:\mathbb{N}\to [n]$ , the **fully-asynchronous** dynamics is

$$x_{v(t)}^{t+1} = f_{v(t)}(x^t), \qquad x_i^{t+1} = x_i^t \quad \forall i \neq v(t)$$

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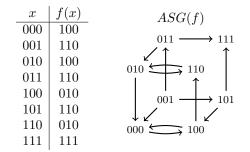
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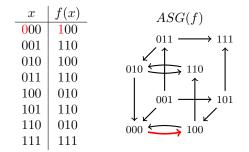
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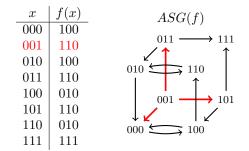
The asynchronous state graph of f, denoted by ASG(f), is the directed graph on  $\{0,1\}^n$  with the following set of arcs:

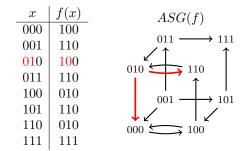
$$\{ x \to \bar{x}^i \mid x \in \{0,1\}^n, i \in [n], x_i \neq f_i(x) \}$$

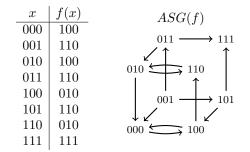
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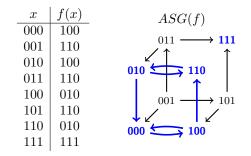






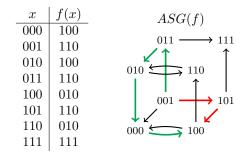






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A path from a state x to a state y is a **direct path** if its length  $\ell$  is equal to the Hamming distance between x and y (so  $\ell \leq n$ ).

#### Definition

The interaction graph of f, denoted G(f), is the signed directed graph on  $\{1, \ldots, n\}$  with the following arcs:

- There is a **positive arc**  $j \rightarrow i$  iff there is a state x such that

$$f_i(x_1, \dots, x_{j-1}, \mathbf{0}, x_{j+1}, \dots, x_n) = \mathbf{0}$$
  
$$f_i(x_1, \dots, x_{j-1}, \mathbf{1}, x_{j+1}, \dots, x_n) = \mathbf{1}$$

- There is a **negative arc**  $j \rightarrow i$  iff there is a state x such that

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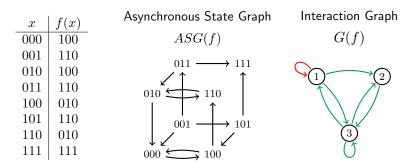
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$$j \rightarrow i \in G(f) \iff f_i(x)$$
 depends on  $x_j$ 

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x	f(x)	Asynchronous State Graph	Interaction Graph
000	100	ASG(f)	G(f)
001	110	$011 \longrightarrow 111$	
010	100		()
011	110	010 110	
100	010		
101	110	$001 \longrightarrow 101$	
110	010		(3)
111	111		G



#### Question

What can be said on ASG(f) according to G(f) ?

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### Results

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Theorem [Robert 1980]

- If  ${\cal G}(f)$  has no cycles then
  - 1. f has a unique fixed point
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#### $\Rightarrow$ complexity comes from cycles of the interaction graph

Two kinds of cycles have to be considered:

- Positive cycles: even number of negative arcs
- Negative cycles: odd number of negative arcs

If all the positive cycles of G(f) can be destroyed by removing k vertices, then ASG(f) has at most  $2^k$  attractors.

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**Corollary** If G(f) has no positive cycles then ASG(f) has a unique attractor

**Theorem on negative cycles** [Richard 2010] If G(f) has **no negative cycles** then ASG(f) has a path from every state x to a fixed point

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#### **Our contribution**

If G(f) has no negative cycles then ASG(f) has a direct path from every state x to a fixed point

### Sketch of proof

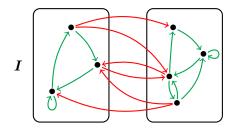
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**Conclusion:** We can suppose that G(f) has only positive arcs This is equivalent to say that f is monotonous:

$$\forall x, y \in \{0, 1\}^n \qquad x \le y \Rightarrow f(x) \le f(y)$$

**Lemma 1** f(0) = 0 and f(1) = 1

Suppose  $f(\mathbf{0}) \neq \mathbf{0}$ , that is,  $f_i(\mathbf{0}) = 1$  for some iThen since f is monotonous,  $f_i(x) = 1$  for all  $x \in \{0, 1\}^n$ Thus  $f_i = cst$ , so i has no in-neighbor in G(f)Thus G(f) is not strong, a contradiction We prove similarly  $f(\mathbf{1}) = \mathbf{1}$ .

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If not there is a path 
$$x \rightsquigarrow z \to \overline{z}^i$$
 with  $z \le y$  and  $\overline{z}^i \le y$ .

Thus  $\bar{z}_i^i = 1$  and  $y_i = 0$ , so  $z \to \bar{z}^i$  increases component *i*.

Thus  $f_i(z) = 1$  and since  $z \le y$  and  $f_i$  is monotonous,  $f_i(y) = 1$ .

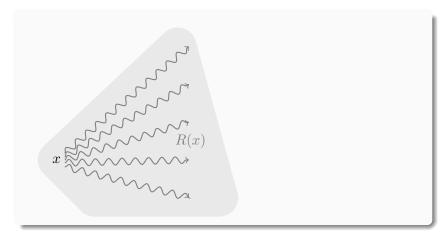
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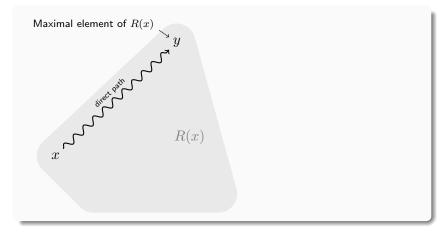
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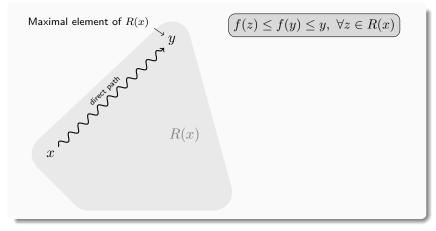
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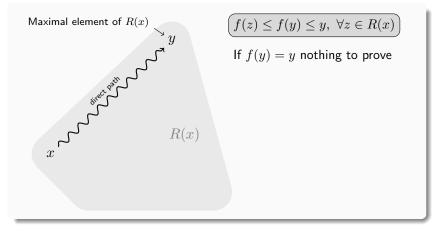
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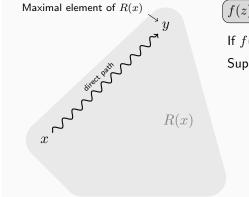






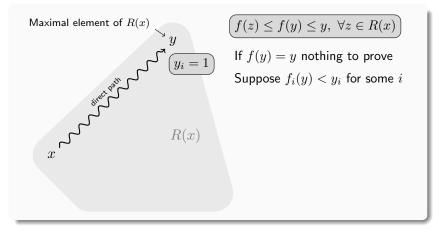


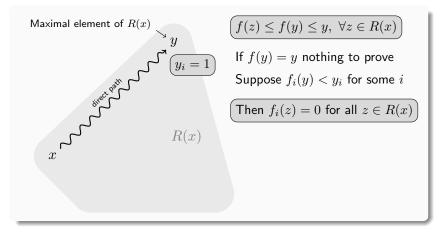
We prove the theorem by induction on the number of ones in x. If x = 0 the theorem is true since f(0) = 0. Suppose that x > 0

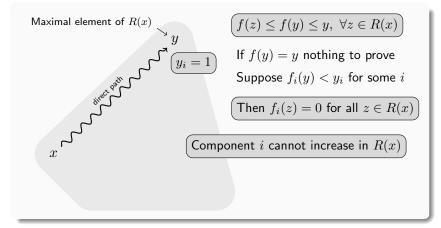


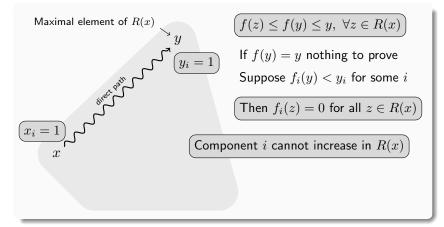
$$f(z) \le f(y) \le y, \ \forall z \in R(x)$$

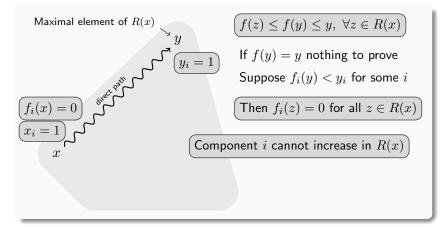
If f(y) = y nothing to prove Suppose  $f_i(y) < y_i$  for some i

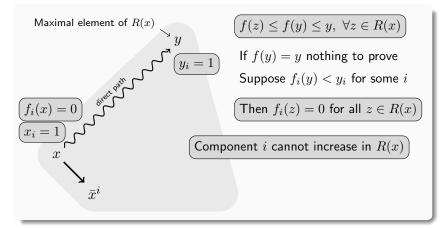


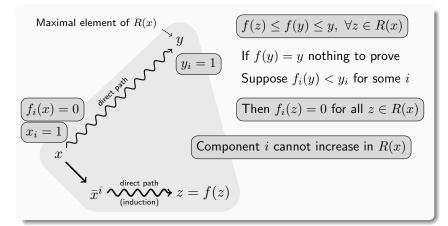


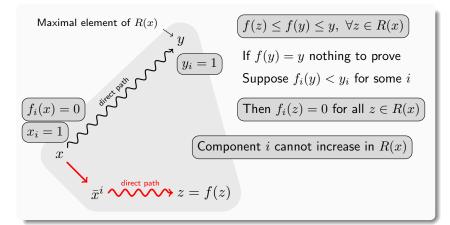


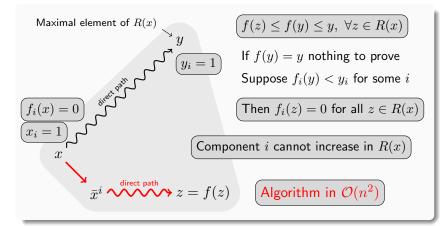












Further results & perspectives

Suppose that G(f) has no negative cycles.

The set of fixed points reachable from x has a *unique* maximal element  $x^+$  and a *unique* minimal element  $x^-$ , which are reachable in at most 2n - 4 transitions (thigh bound).

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Can we obtain upper/lower bounds on the number of fixed points reachable from x according to  ${\cal G}(f)$  ?

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## Thank you!