

Reduction of Discrete Dynamical Systems
&
Linear Network Coding

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(arXiv:1512.5310)

① Introduction

② Approximation of $\max(G, \rho)$

③ Reduction

④ Application to linear network coding

⑤ Conclusion

A *finite dynamical system* with n components is a function

$$f: A^n \rightarrow A^n \quad x = (x_1 \dots x_n) \mapsto f(x) = (f_1(x) \dots f_n(x))$$

where A is a finite set. Here, $A = \{0, 1, \dots, p-1\} = [p]$ for some $p \geq 2$.

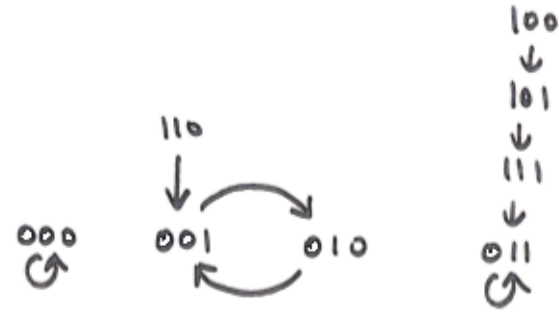
The *interaction graph* of f is the directed graph $G(f)$ on $\{1 \dots n\}$ defined by

$$j \rightarrow i \in G(f) \iff f_i \text{ depends on } x_j$$

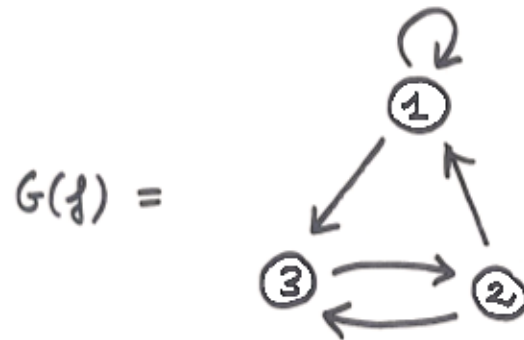
Example with $n=3$ and $A=\{0,1\}=[2]$

x	$f(x)$
000	000
001	010
010	001
011	011
100	101
101	111
110	001
111	011

$$\begin{cases} f_1(x) = x_1 \wedge \overline{x_2} \\ f_2(x) = x_3 \\ f_3(x) = x_1 \vee x_2 \end{cases}$$



The interaction graph of f is



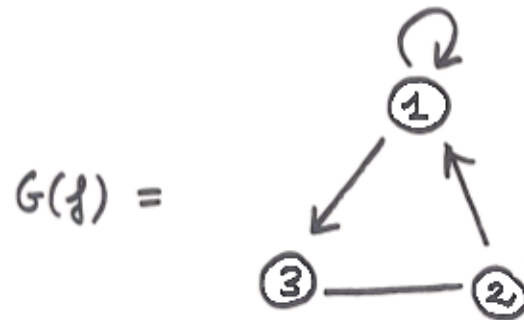
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Many Applications:

- Neural networks (McCulloch & Pitts 1943)
- Gene networks (Kauffman 1969, Thomas 1973)
- Network coding (Ahlsweide et al, 2000)

In the context of gene networks:

- First reliable information are often on the interaction graph $G(f)$
- Fixed points of f have often a biological meaning

What can be said on the fixed points of f according to $G(f)$?

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- First reliable information are often on the interaction graph $G(f)$
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What can be said on the fixed points of f according to $G(f)$?

$\max(G, p) =$ maximum number of fixed points among all the systems

$$f: [p]^m \rightarrow [p]^m \text{ with } G(f) \subseteq G$$

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= packing number of G

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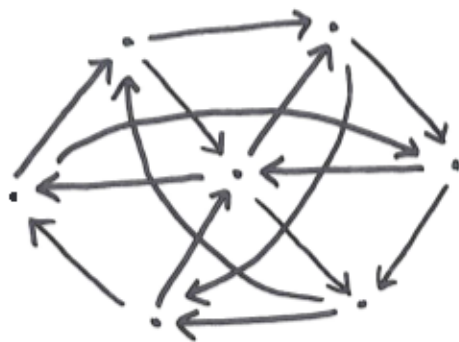
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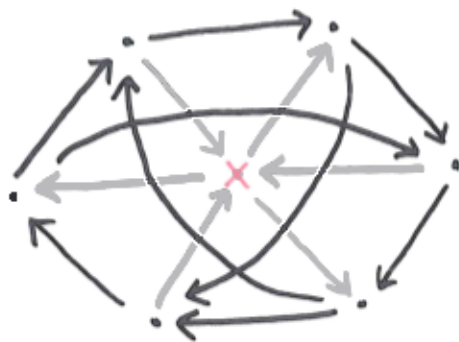
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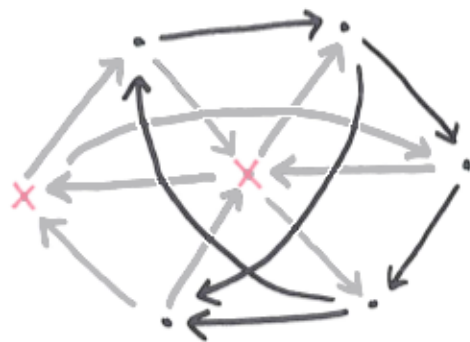
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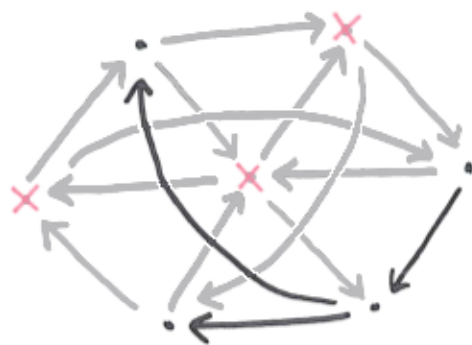
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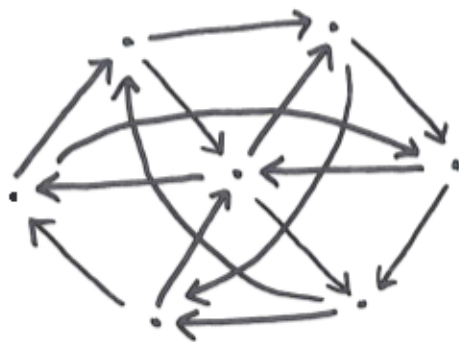
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$$\nu(G) = 1 \Rightarrow \tau(G) \leq 3 \quad (\text{McGuire 1993})$$

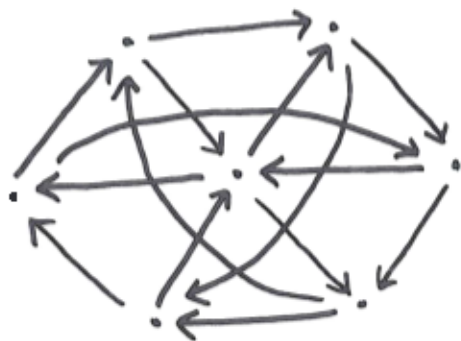
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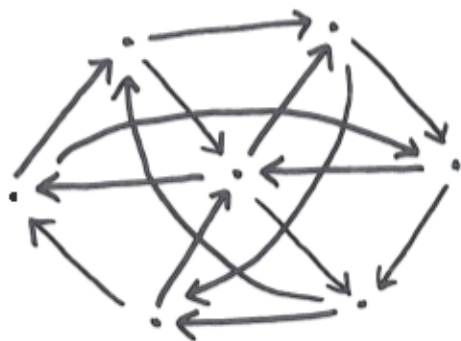
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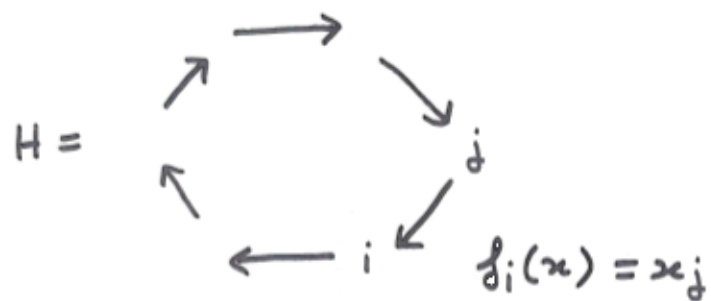
Theorem (Aracena 2004, Rii 2007)

$$p^{v(G)} \leq \max(G, p) \leq p^{T(G)}$$

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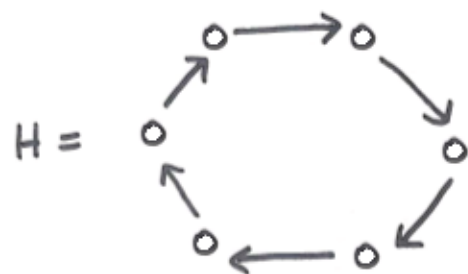
Lower bound



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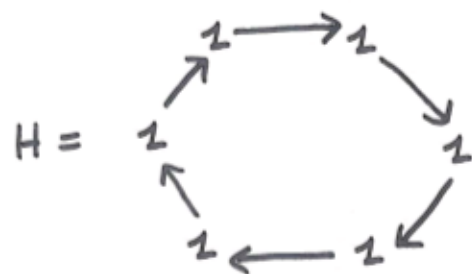
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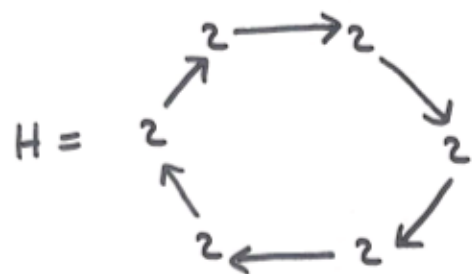
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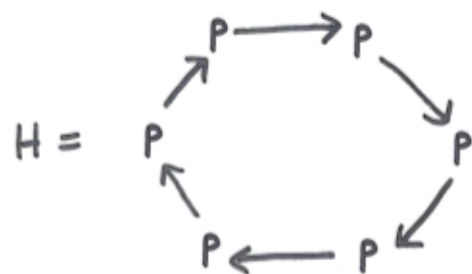
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Lower bound



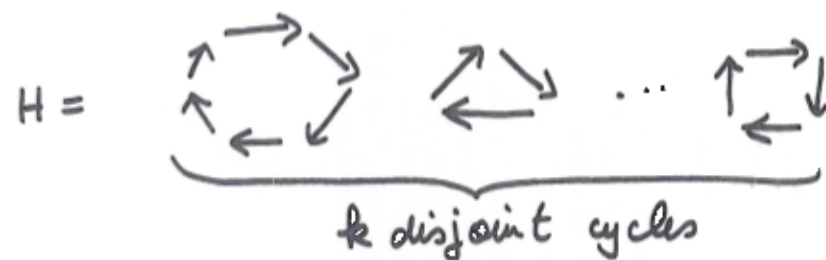
f has p fixed points

$$p \leq \max(H, p)$$

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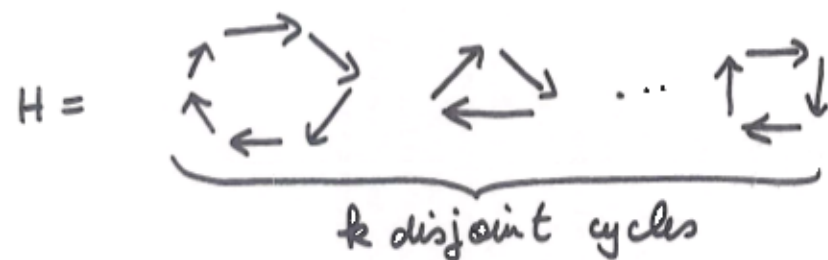


$$p^k \leq \max(H, p)$$

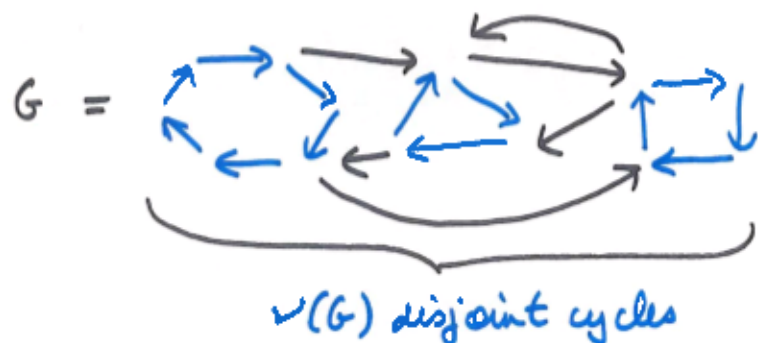
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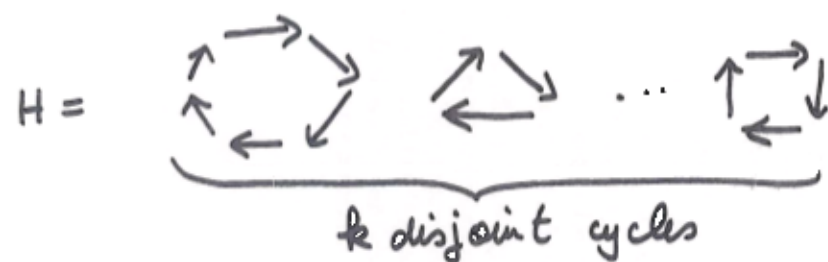
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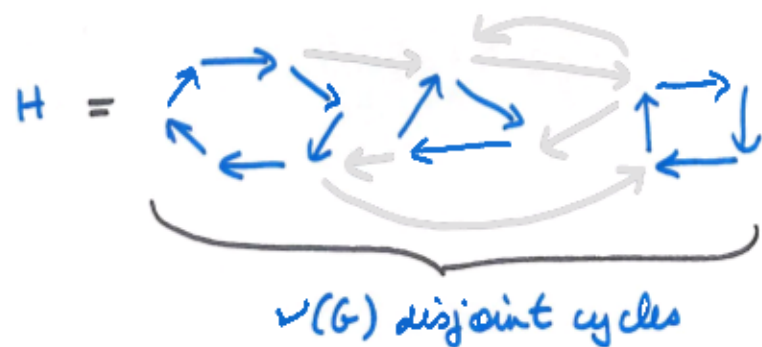
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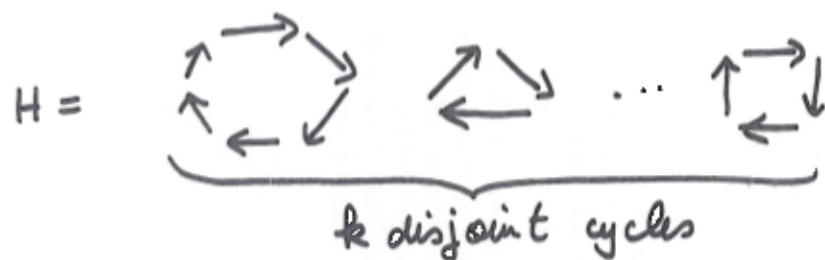


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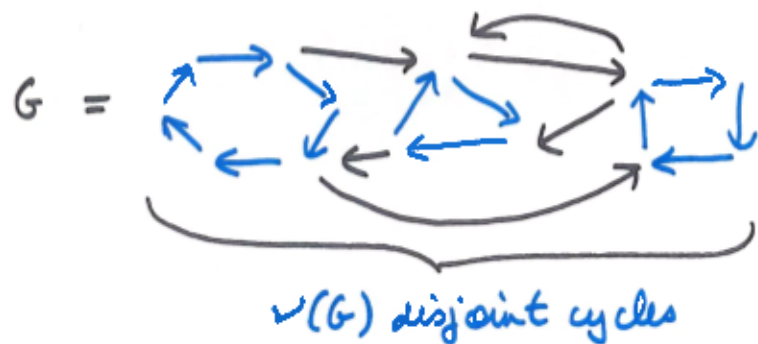
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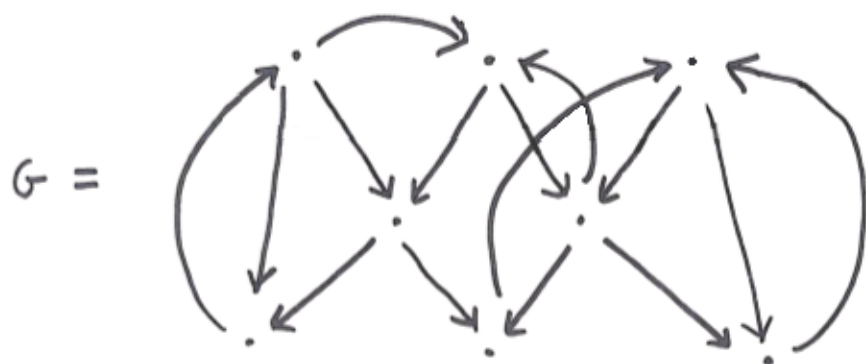


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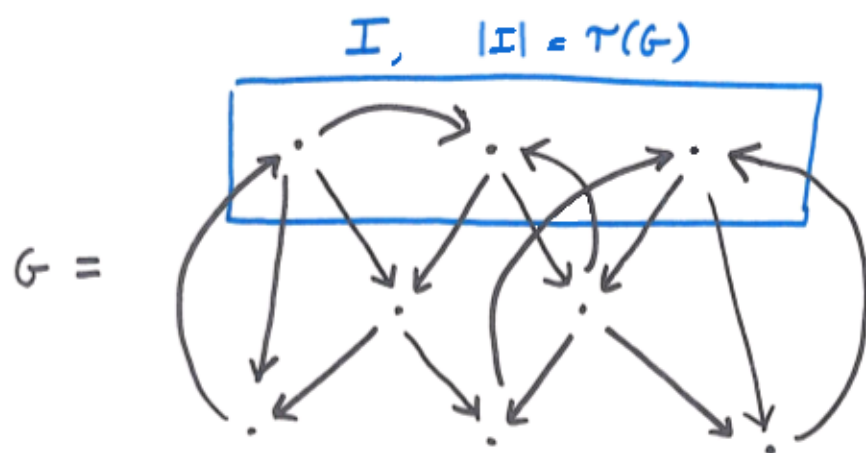
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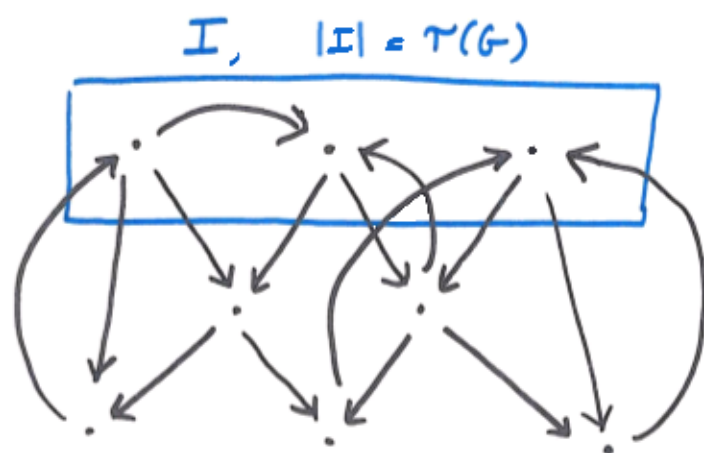


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Let $f: [p]^m \rightarrow [p]^m$
with $G(f) \subseteq G =$

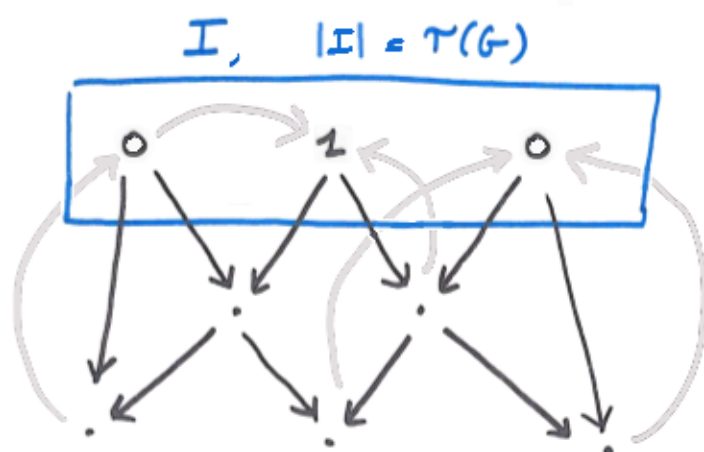


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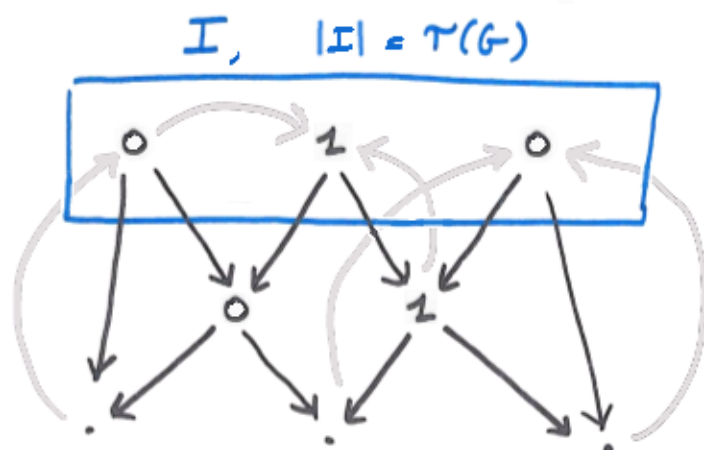
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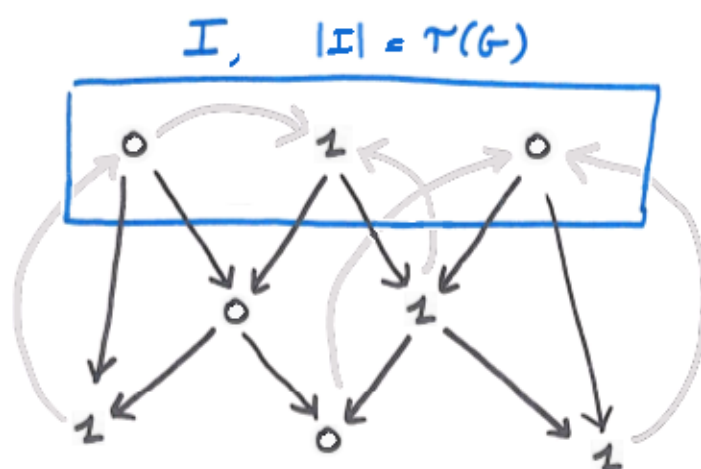
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 \downarrow Diffusion (depends on f)
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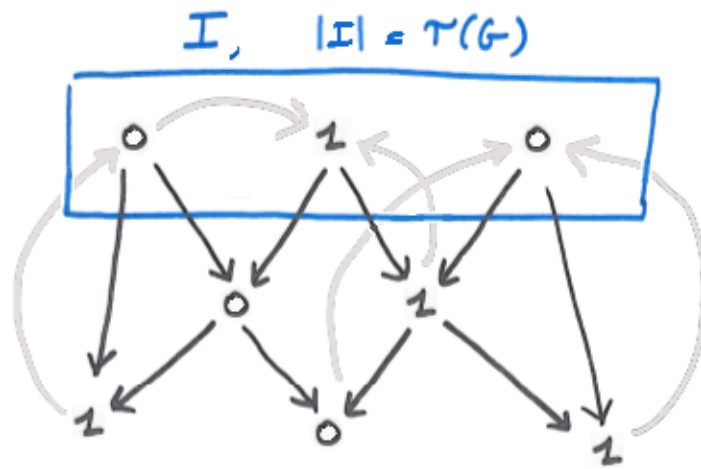
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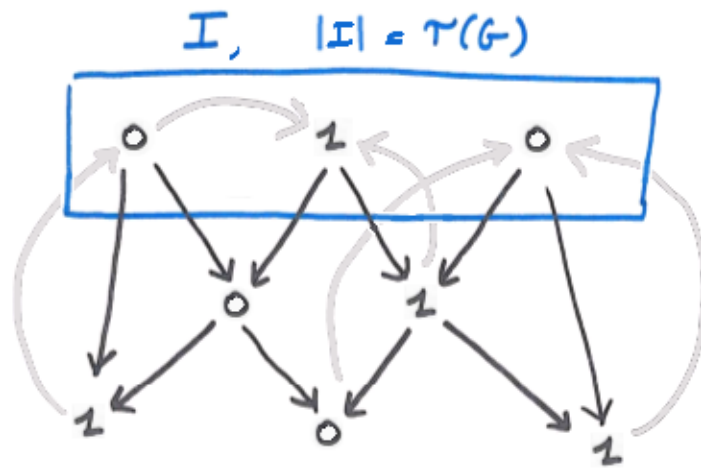
All the fixed points of f are in $X = \{x^* \mid x \in [p]^I\}$

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f has at most $|X| \leq p^{|I|} = p^{\tau(G)}$ fixed points

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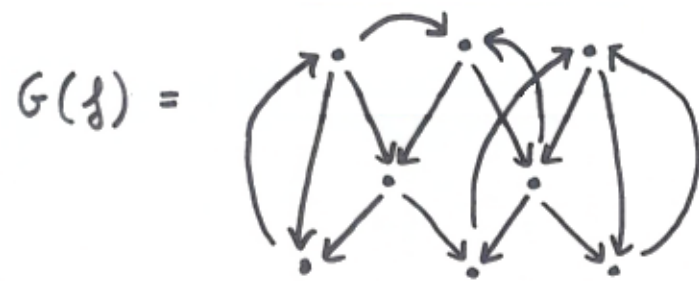
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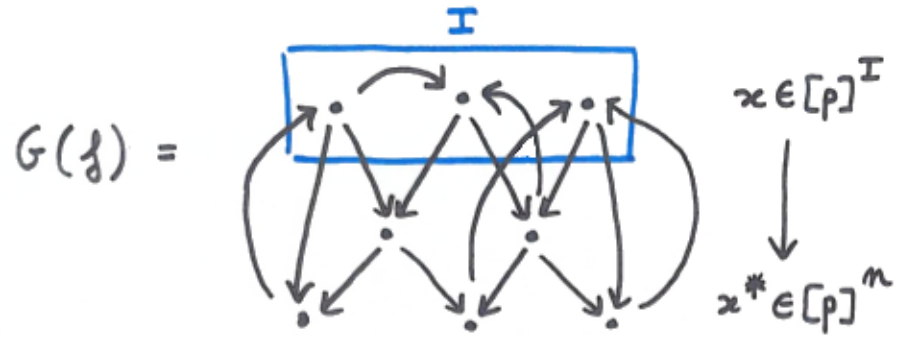
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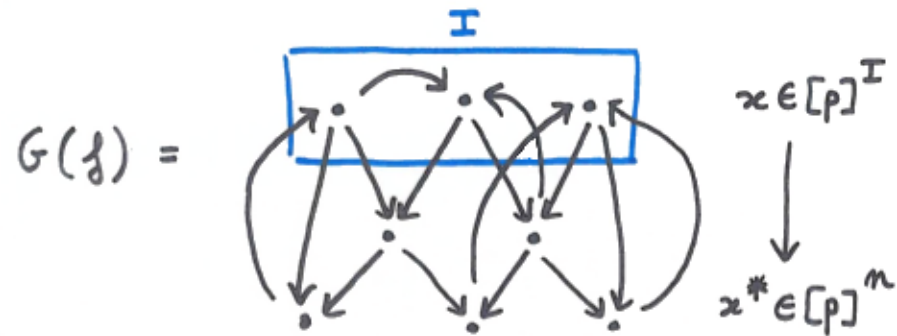
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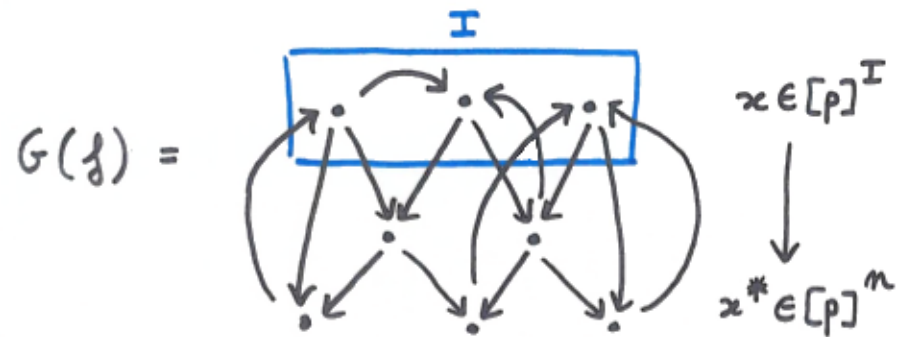
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The reduced system $f^I: [p]^I \rightarrow [p]^I$ is defined by

$$f^I(x) = f(x^*)_I$$

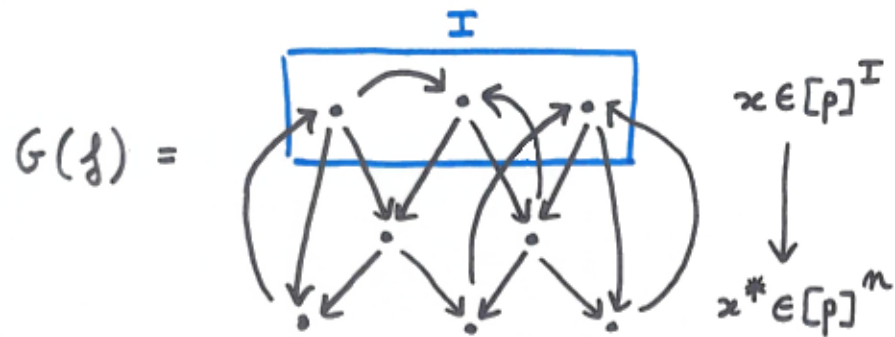
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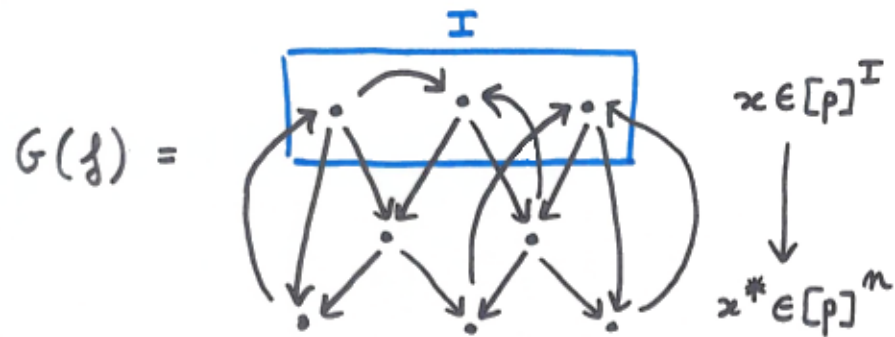
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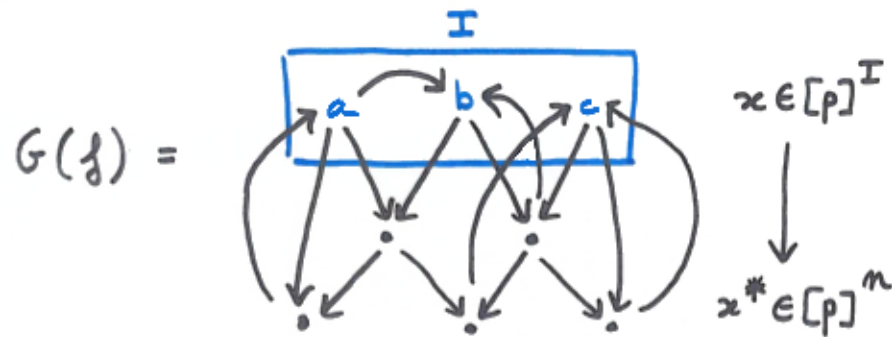
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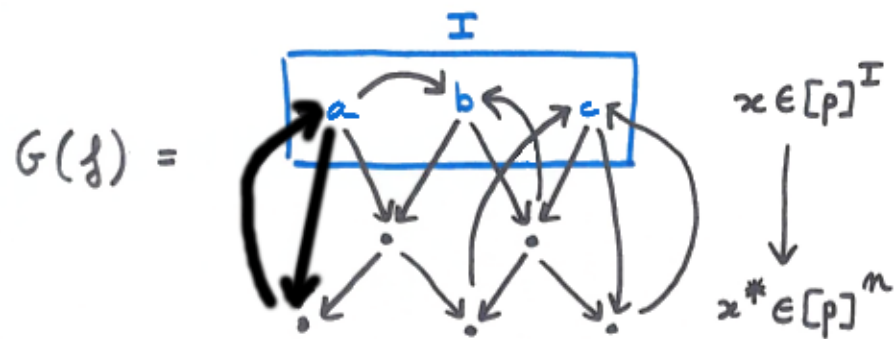
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- There is an arc $j \rightarrow i$ if $G(f)$ has a path from j to i with no internal vertex in I

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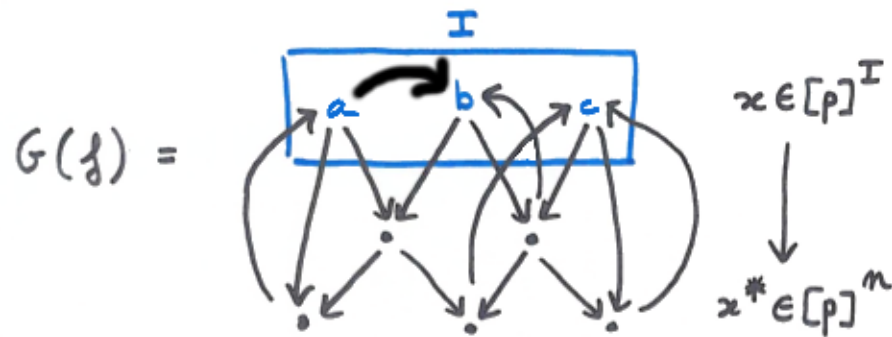
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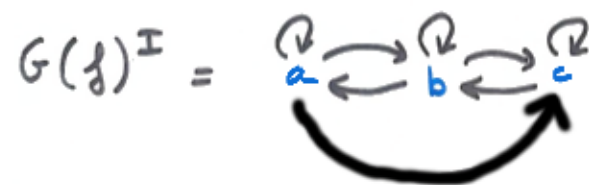
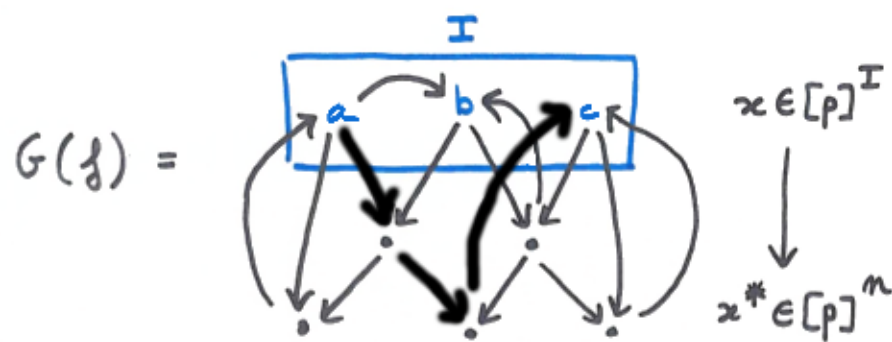
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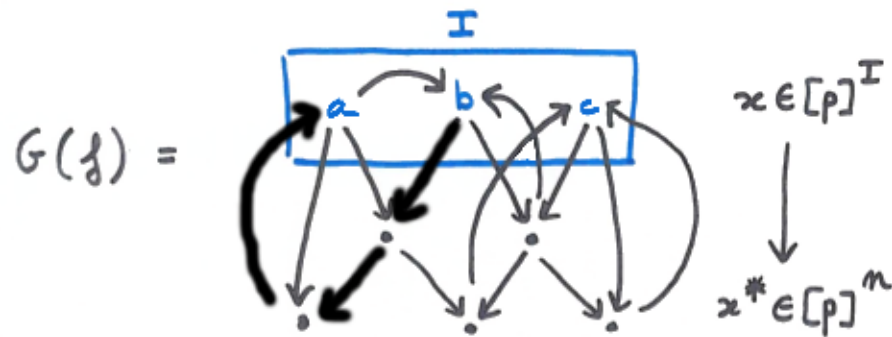
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f and f^I have the same number of fixed points

$$f^I(x) = x \iff f(x^*) = x^*$$

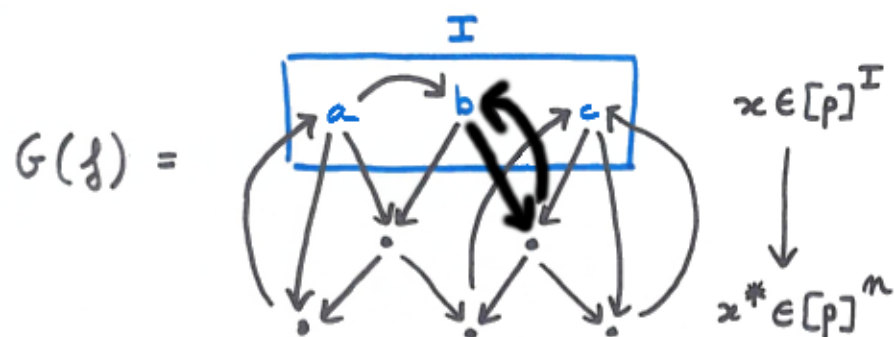
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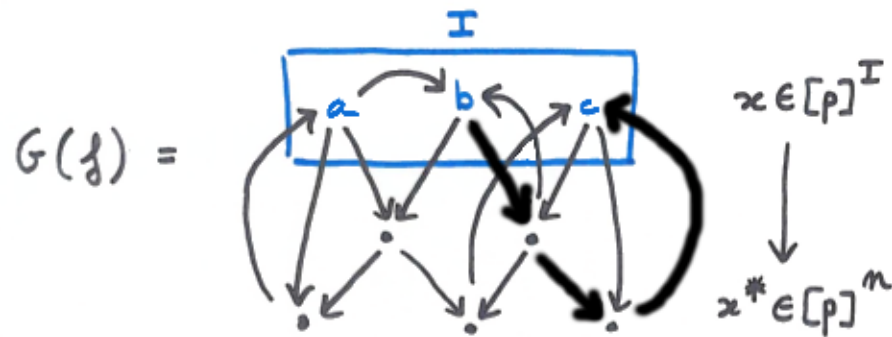
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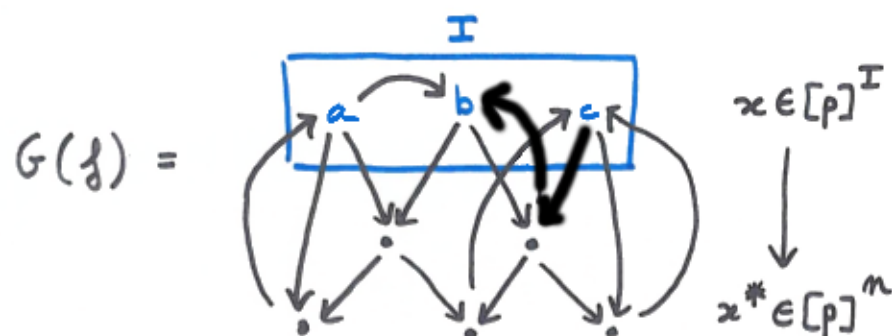
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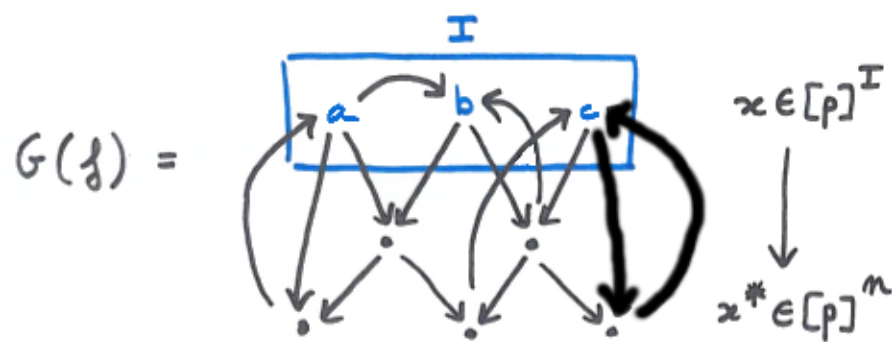
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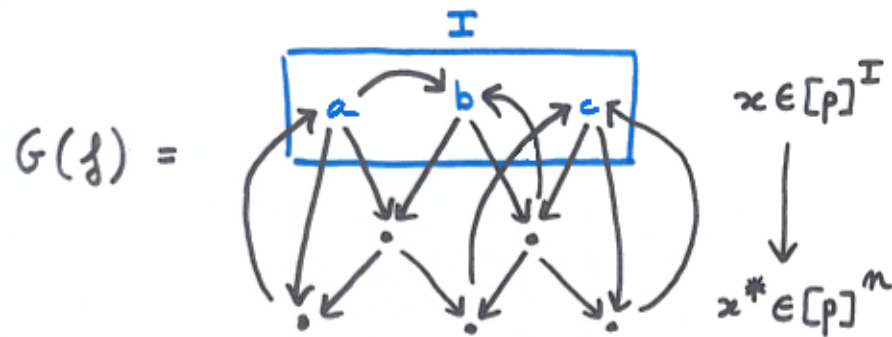
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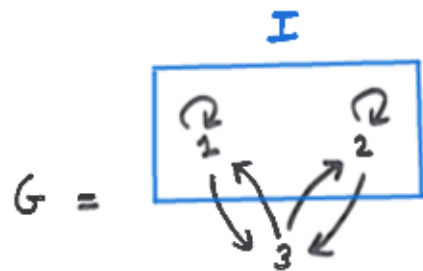
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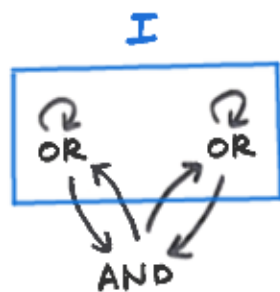
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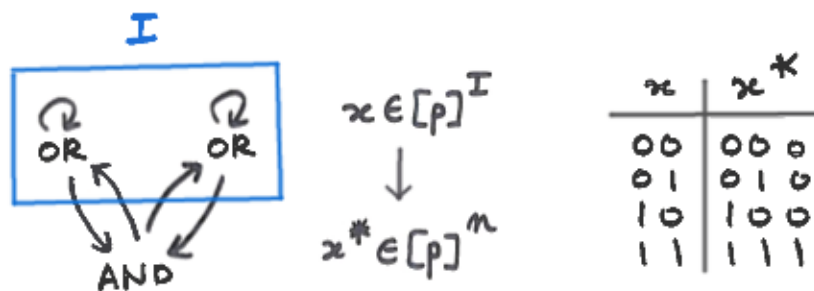
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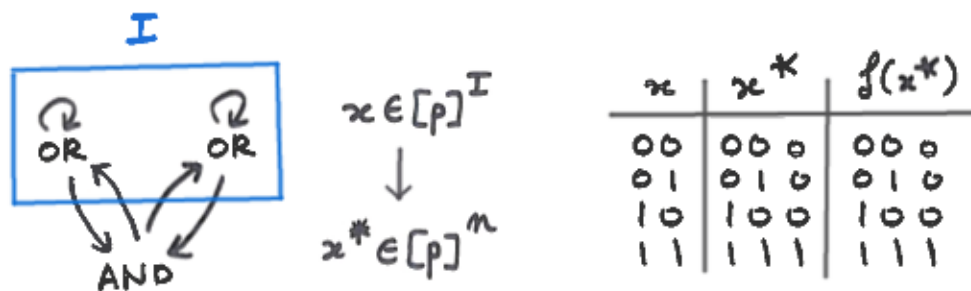
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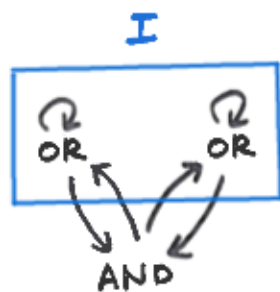
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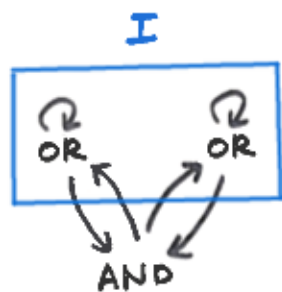
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x	x^*	$f(x^*)$	$f^I(x)$
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01	010	010	01
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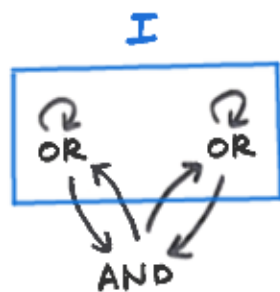
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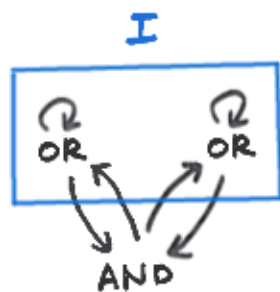
$G(f^I) = \begin{matrix} \curvearrowright & \curvearrowright \\ 1 & 2 \end{matrix}$

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$G(f)^I = \begin{matrix} \curvearrowright & \curvearrowright \\ 1 & \leftrightarrow 2 \end{matrix}$

① Introduction

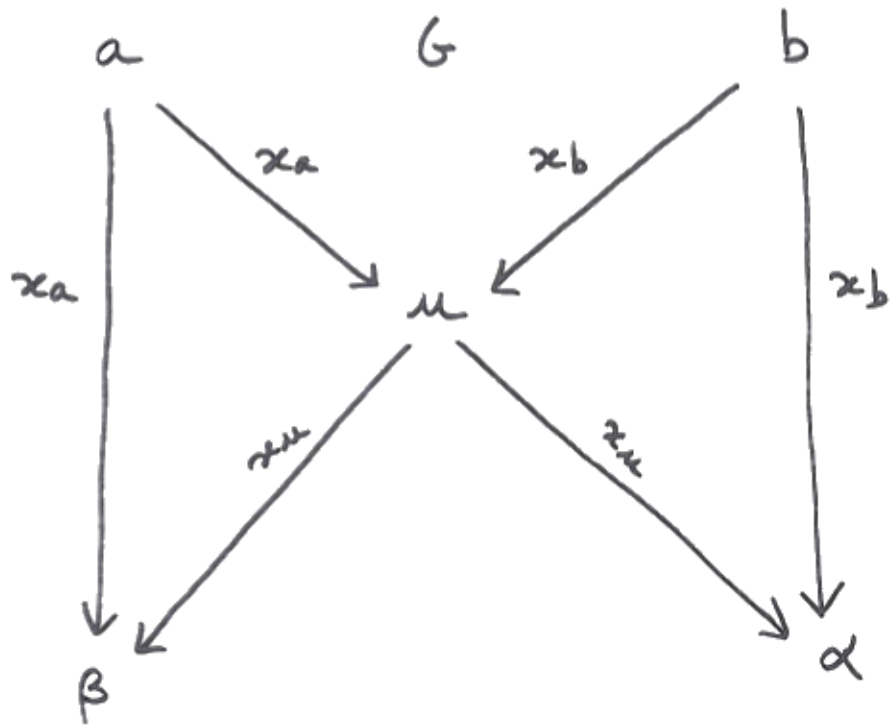
② Approximation of $\max(G, \rho)$

③ Reduction

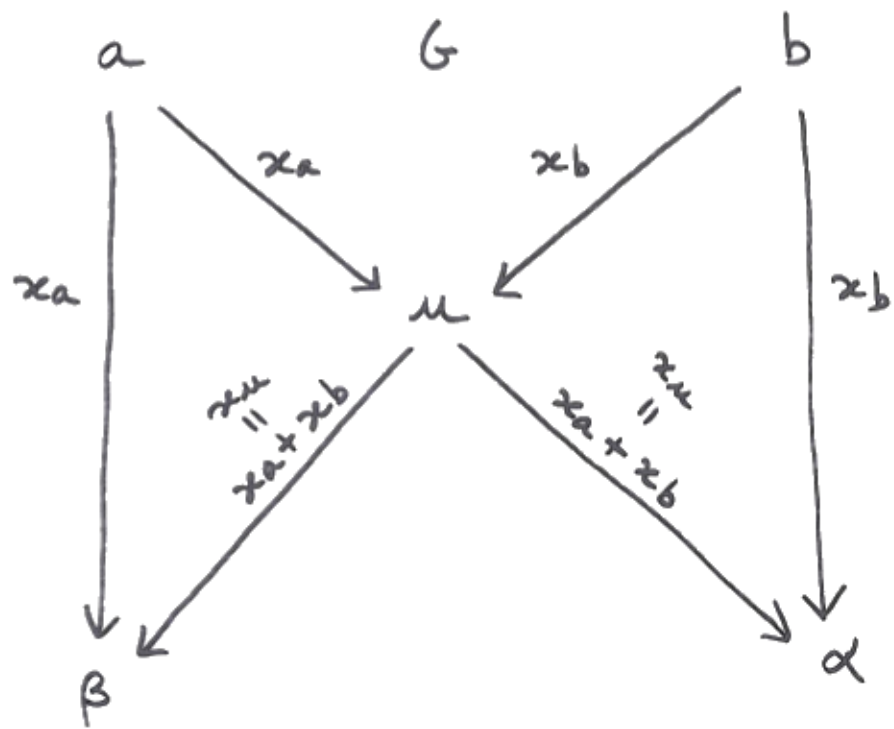
④ Application to linear network coding

⑤ Conclusion

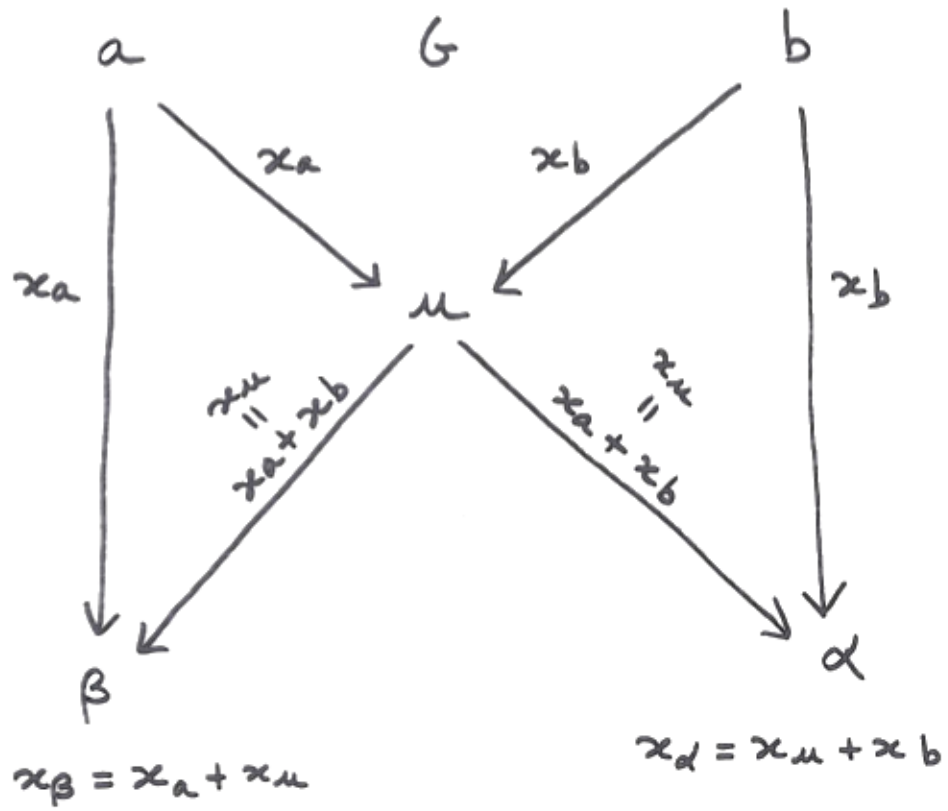
Network Coding



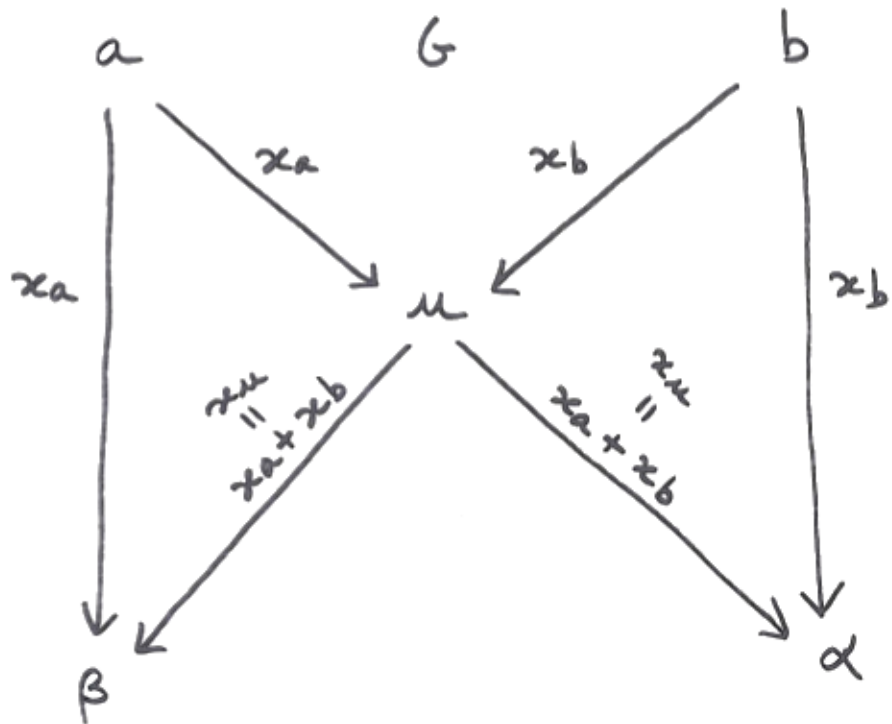
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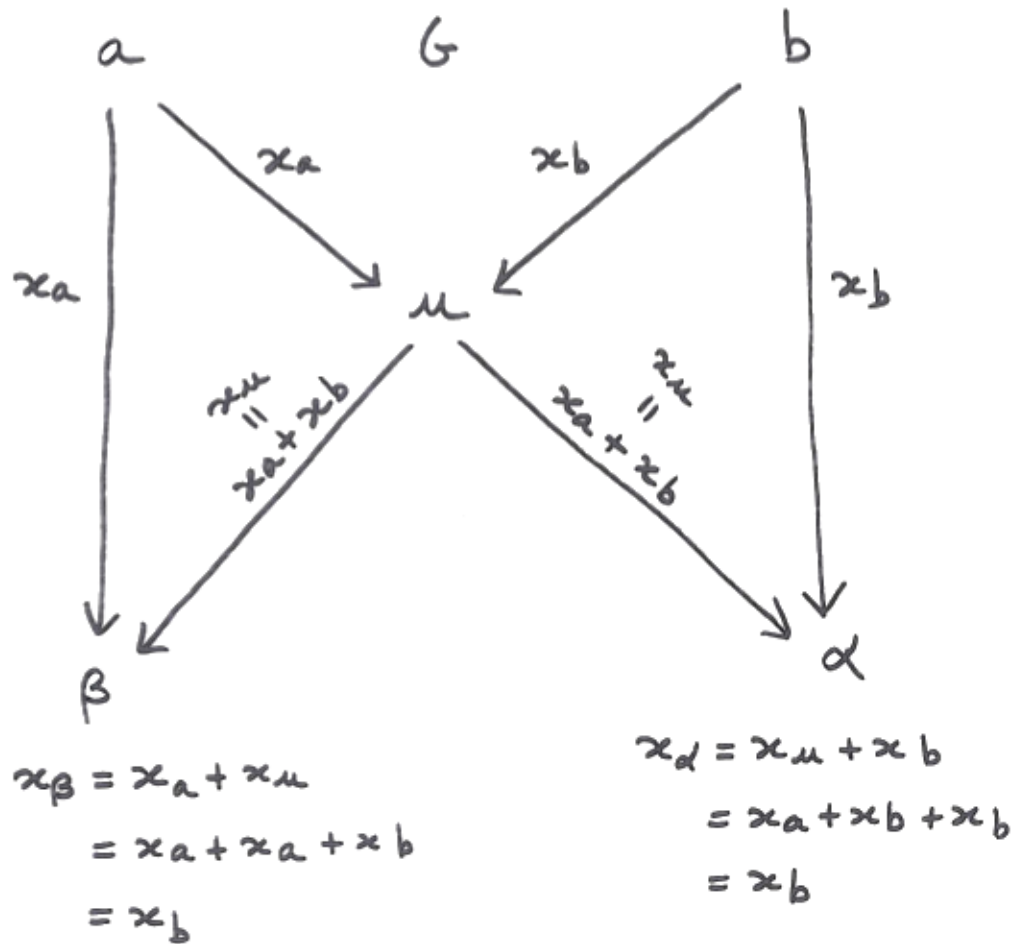
Network Coding



$$\begin{aligned}
 x_\beta &= x_a + x_u \\
 &= x_a + x_a + x_b \\
 &= x_b
 \end{aligned}$$

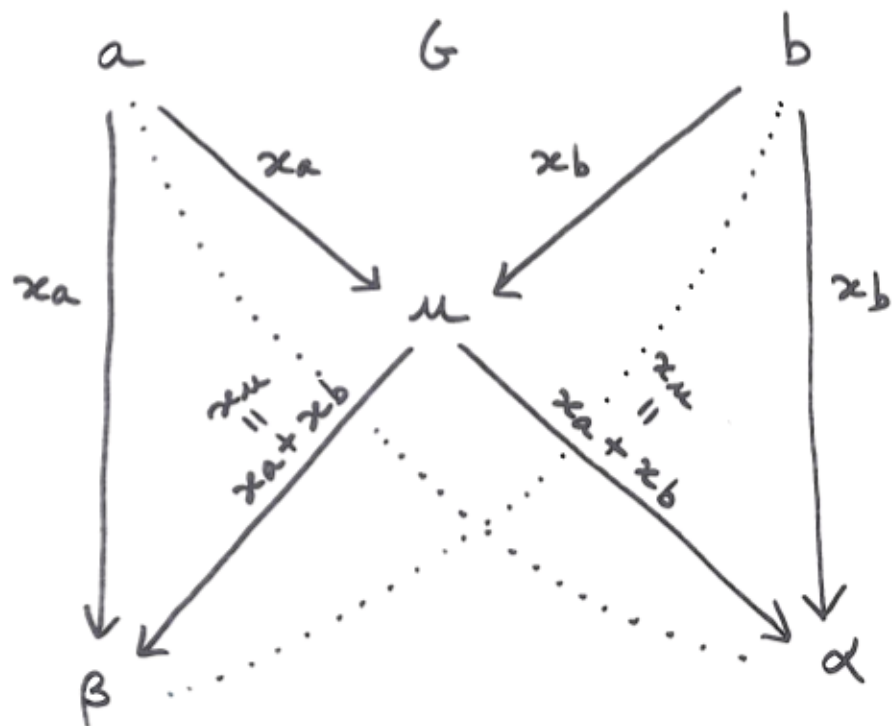
$$\begin{aligned}
 x_\alpha &= x_u + x_b \\
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Network Coding



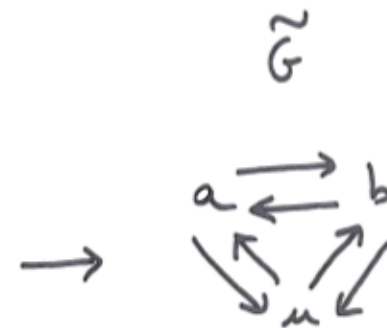
G is solvable

Network Coding



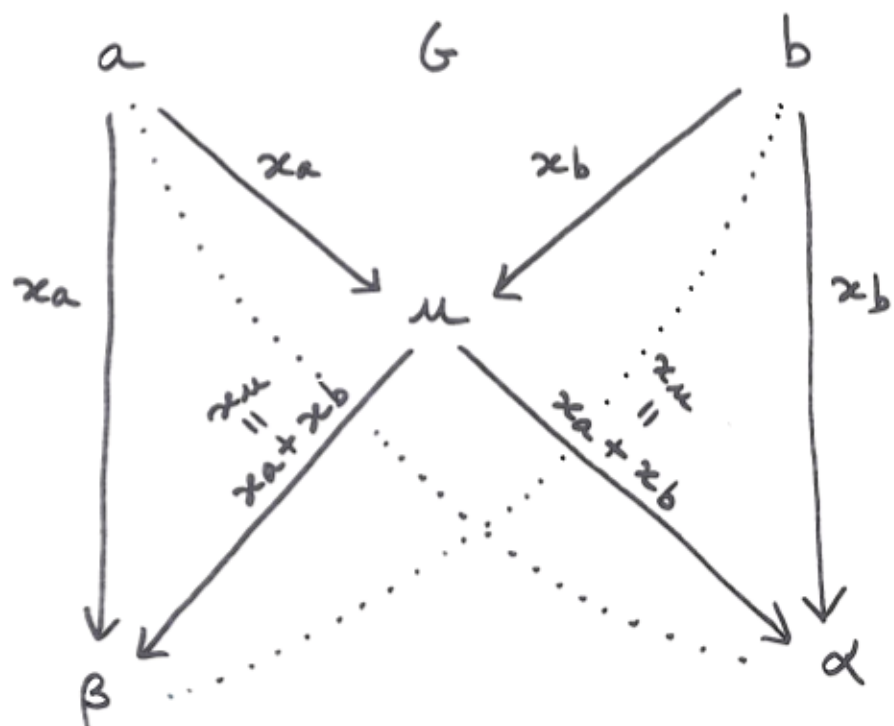
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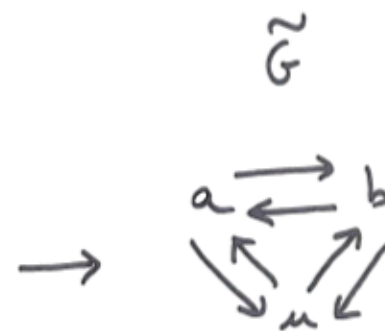
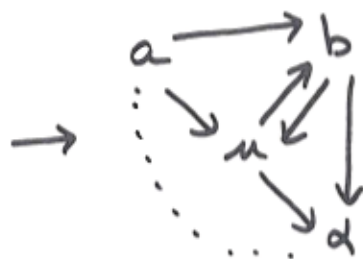
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G is solvable

\Leftrightarrow

$$\max(\tilde{G}, p) = p^{\tau(\tilde{G})} \text{ for some } p$$

Central question in network coding

Which are the interaction graphs G such that

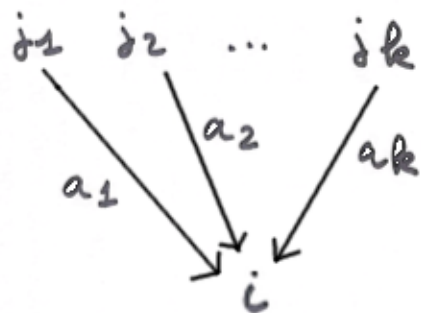
$$\max(G, p) = p^{\tau(G)} \quad \text{for some } p \quad (\text{solvable for some } p)$$

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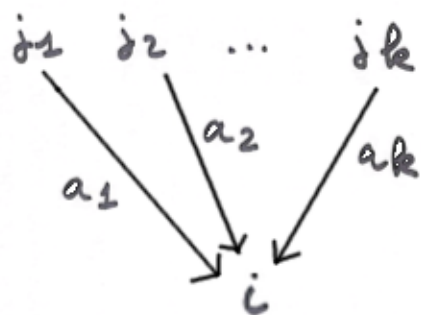
$$f_i(x) = \sum_{l=1}^k a_l x_{j_l} \pmod{p}$$

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$\max L(G, p) =$ maximum number of fixed points among all the linear systems

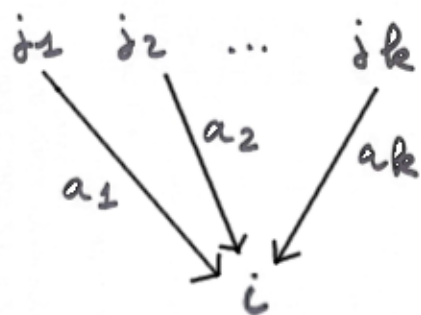
$$f: [p]^m \rightarrow [p]^m \quad \text{with } G(f) \subseteq G$$

Central questions in network coding

Which are the interaction graphs G such that

- $\max(G, p) = p^{\tau(G)}$ for some p (solvable for some p)
- $\max L(G, p) = p^{\tau(G)}$ for some p (linearly solvable for some p)

The number of fixed points is often maximized by linear systems



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Theorem (Fanchon, Gadouleau, Richard 2014)

Let G be an undirected triangle-free graph. Then the following are equivalent:

① $\max L(G, p) = p^{T(G)}$ for some p .

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Remarks

• Since $p^{\nu(G)} \leq \max_L(G, p) \leq p^{\tau(G)}$ we have $\textcircled{3} \Rightarrow \textcircled{2} \Rightarrow \textcircled{1}$. The new result is $\textcircled{1} \Rightarrow \textcircled{3}$.

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Example



$$\nu(C_5) = 2$$

$$\tau(C_5) = 3$$

thus $\max_L(G, p) < p^{\tau(G)}$ for all p .

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Example



$$\begin{aligned}\nu(C_5) &= 2 \\ T(C_5) &= 3\end{aligned}$$

thus $\max_L(G, p) < p^{T(G)}$ for all p

C_5 is not linearly solvable

$$\max_L(G, p) = p^{T(G)} \text{ for some } p \Rightarrow V(G) = T(G)$$

$$\max_{L(G, p)} = p^{\tau(G)} \text{ for some } p \Rightarrow \nu(G) = \tau(G)$$

• Let $f: [p]^m \rightarrow [p]^m$ be a linear system with $G(f) \subseteq G$ and $\text{fix}(f) = p^{\tau(G)}$

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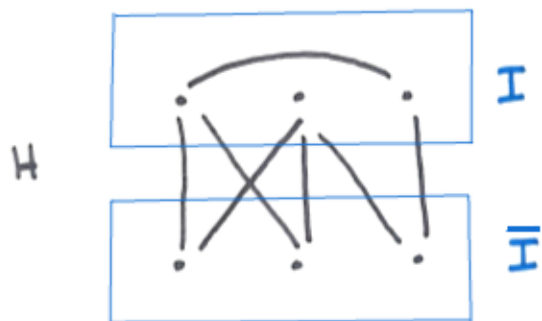
- Let $f: [p]^m \rightarrow [p]^m$ be a linear system with $G(f) \subseteq G$ and $\text{fix}(f) = p^{\tau(G)}$
- Let H be the undirected version of $G(f)$ $G(f) \subseteq H \subseteq G$

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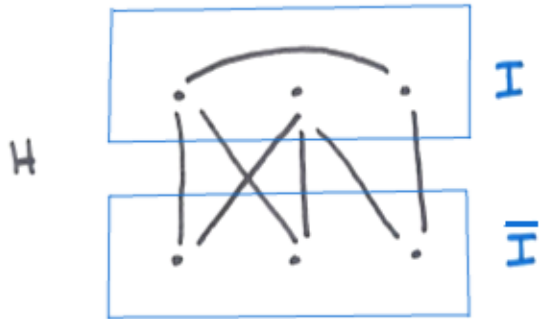
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- Let I be a minimal vertex cover of H ($|I| = \tau(H)$) \bar{I} is an independent set



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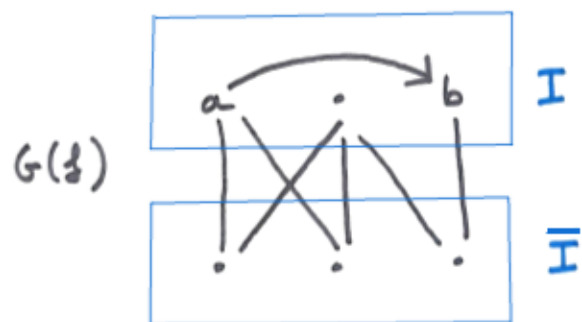
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- Suppose that I is not an independent set. Then:

$$\max_L(G, p) = p^{\tau(G)} \text{ for some } p \Rightarrow \nu(G) = \tau(G)$$

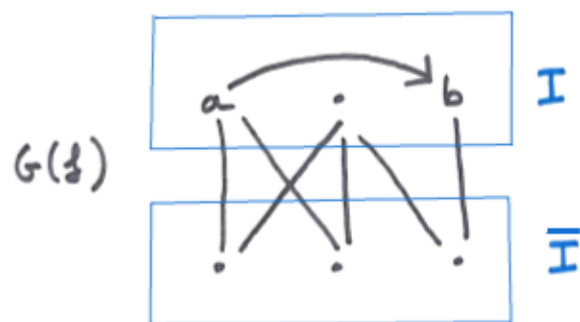
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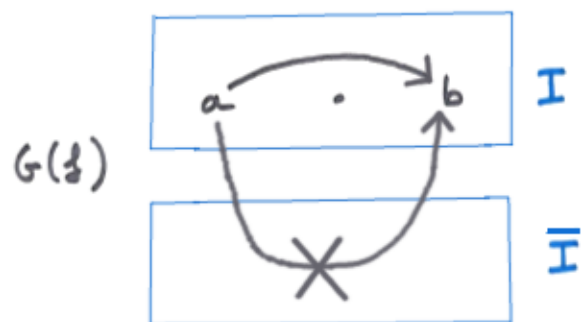


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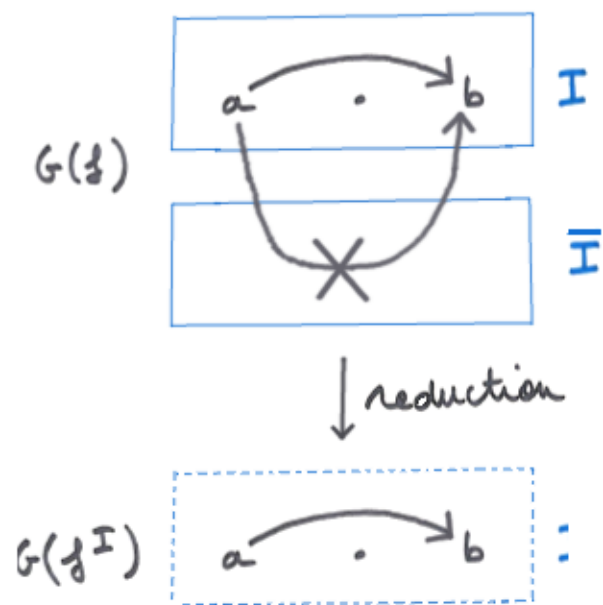


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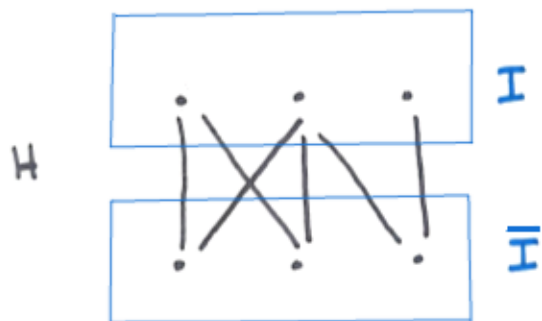
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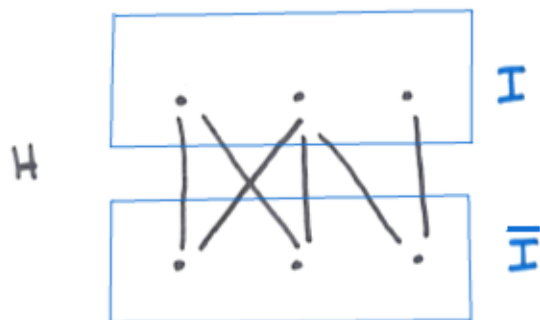


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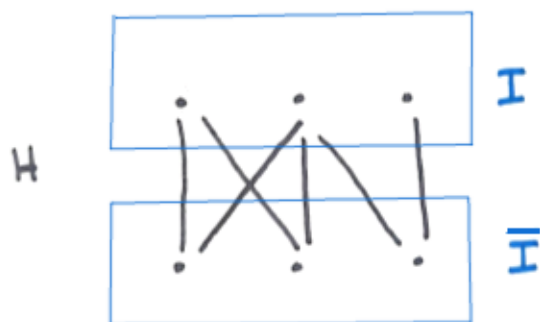
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• Since $\nu(H) \leq \nu(G) \leq \tau(G) = \tau(H)$ we obtain $\nu(G) = \tau(G)$

① Introduction

② Approximation of $\max(G, \rho)$

③ Reduction

④ Application to linear network coding

⑤ Conclusion

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↳ Naldi's talk tomorrow!