Scalability Analysis of Mini-Cluster Jetson TX2 for Training DNN Applied to Healthcare

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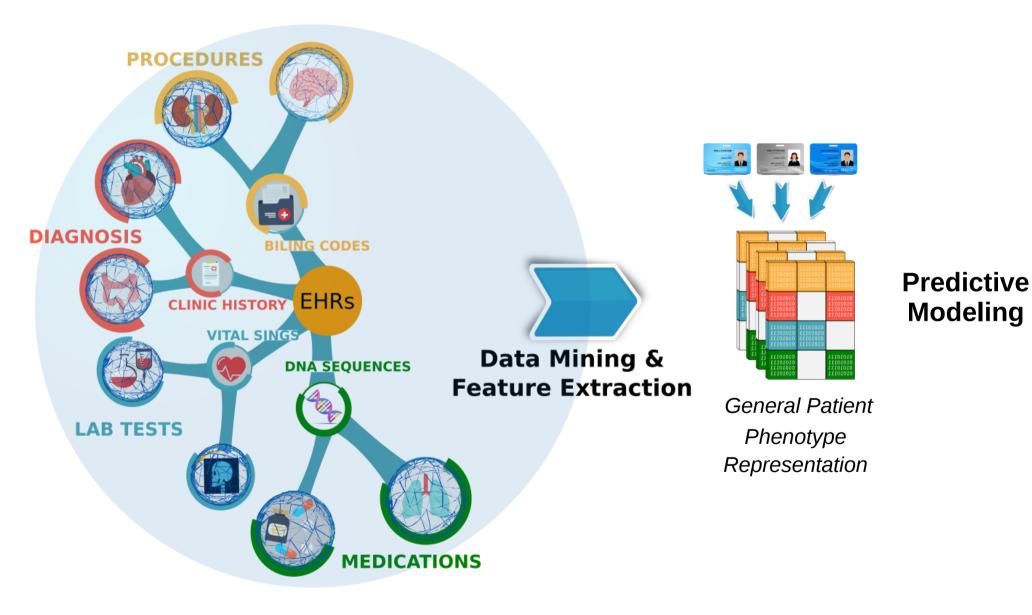






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Motivation: Health Care Decision-Making



- A common challenge in healthcare today is that physicians have access to massive amounts of data on patients, but have short time to analyze all of them.
- One limitation is that hospitals without robust computational systems for processing, storing and drawing conclusions requires to outsource the clinical tasks and that is a risk for privacy clinical data.

Developing a Green Intelligence Medical System to derivate a patient representation for predict general medical targets and improving the computational resources usage.

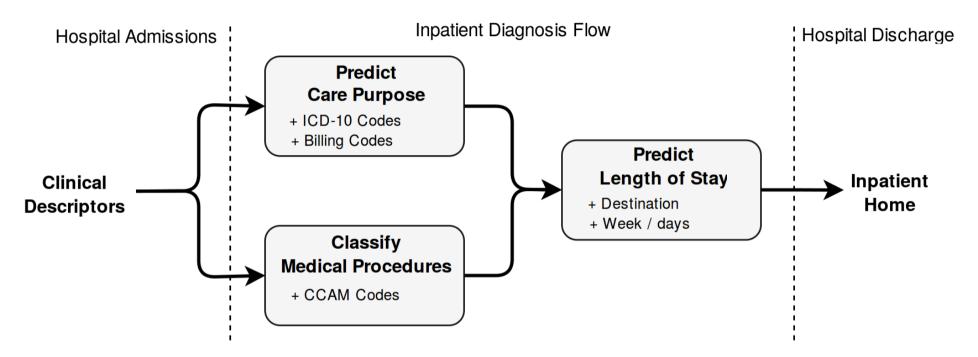


Provides three high-level features:

- 1) A framework to build full Deep Neural Networks (DNN) workflow;
- 2) An energy-monitoring tool for workload characterization;
- 3) A distributed processing for training DNN on Jetson TX2 Mini-Clusters.

Case Study: Predict the Medical Future of Hospitalized Patients

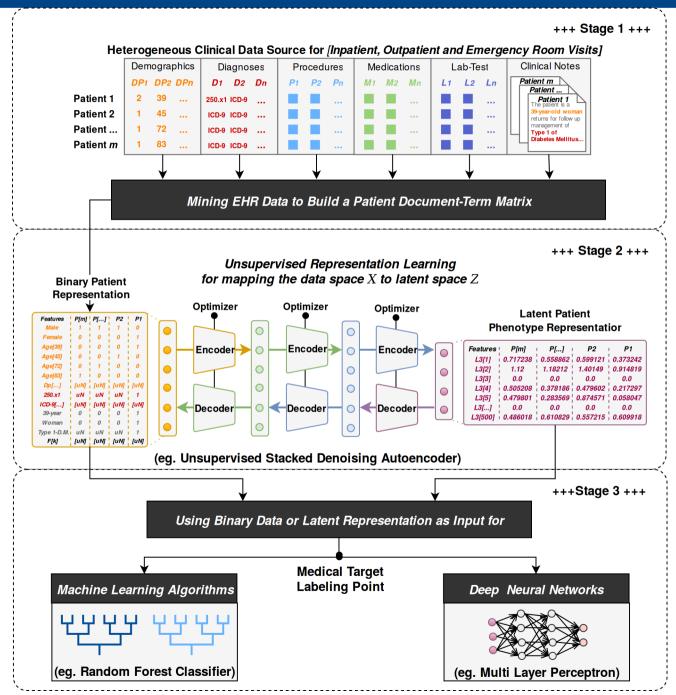
Medical Target Pipeline



	Diagnosis-related Group	ICD-10 Codes	Definition
Patient 1	Morbidity Principal	R402	Unspecified coma
	Etiology	I619	Nontraumatic intracerebral hemorrhage, unspecified
$Medical \ Target$	Care Purpose	Z515	Encounter for palliative care
Label used	Clinical Major Category	20	Palliative care
Patient 2 Morbidity Principal Etiology		R530 C20	Neoplastic (malignant) relate fatigue Malignant neoplasm of rectum
$Medical \ Target$	Care Purpose	Z518	Encounter for other specified aftercare
Label used	Clinical Major Category	60	Other disorders

5

DiagnoseNET: Framework to automize the Patient Phenotype Representation

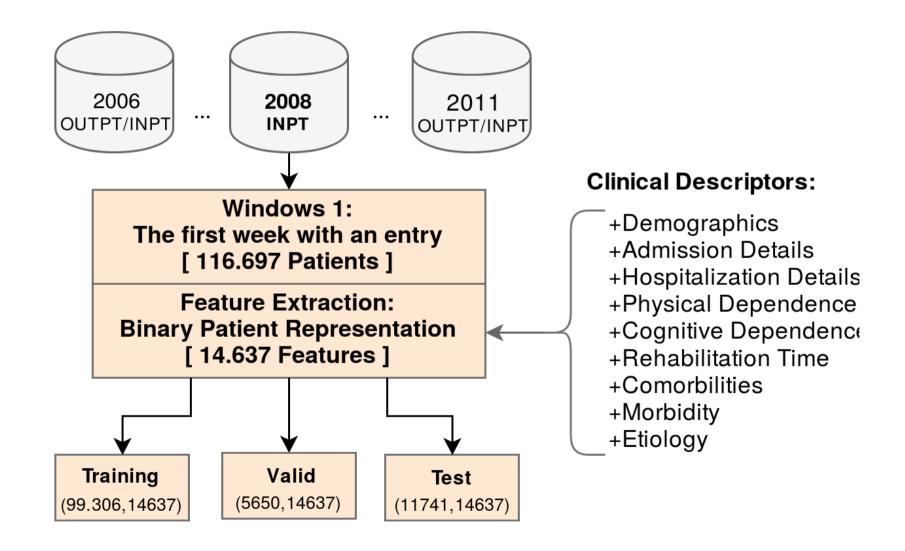


3. Adapted from: Deep Patient: An Unsupervised Representation to Predict the Future of Patients from the Electronic Health Records. By Riccardo Miotto et al. SCIENTIFIC REPORTS, 2016.

Mining Electronic Health Records To Build A Patient Entity-Term Matrix

PMSI-PACA Clinical Dataset

As Input we are using **result features** that describe the patient clinical descriptors to predict the medical targets.



Serialized a Patient Record in a Clinical Document Architecture Schema

Patients	x1_demographics			x4_physical_dependance			x7_related_diagnoses		
ratients	gender		age	feeding		displacement	Das1		Das 3
Patient 1	2		61	4		2	Z431		Z501
Patient 2	2		65	4		2	J459		F322
	•••			•••					
Patient m	1		95	1		2	C259		F322

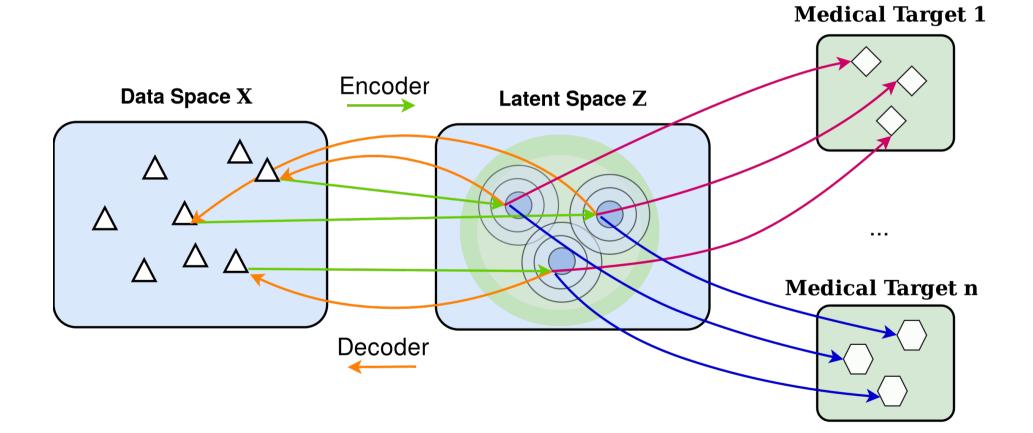
Build a Term-Document Matrix or Binary Patient Representation

Patients	x1 :demographics			x4 :physical_dependance			x7 :related_diagnoses		
Fattents	[1 :male]	[2 :female]	60-74	[4 :Assistance]		[2 :normal_transfer]	Z431		F322
Patient 1	0	1	1	1	•••	1	1		0
Patient 2	0	1	1	1	•••	1	0		1
••••	•••	•••	•••		•••	•••			
Patient m	1	0	0	0	•••	1	0		1

Unsupervised Patient Phenotype Representation

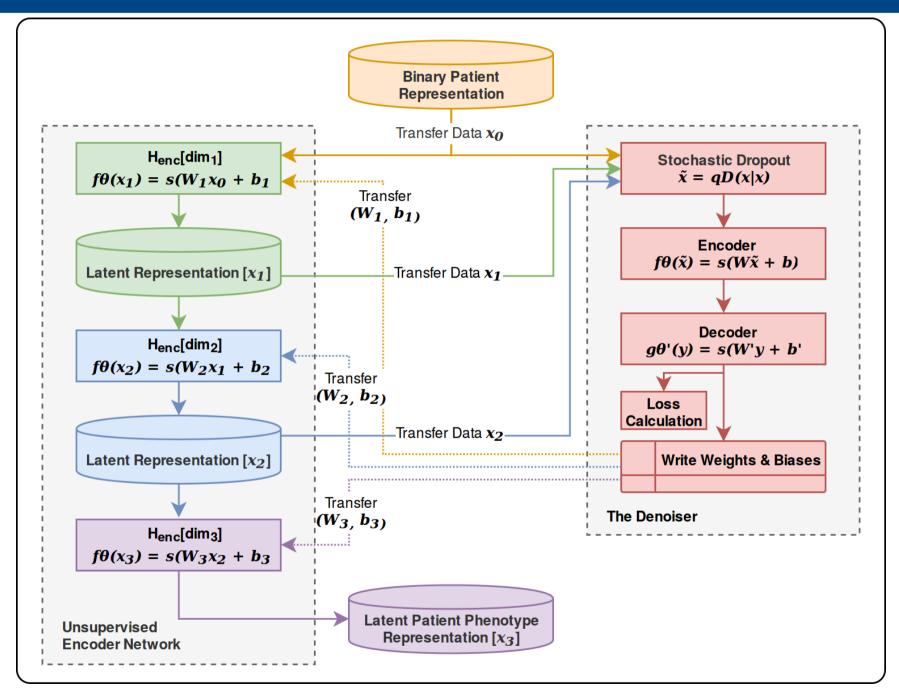
Unsupervised Patient Phenotype Representation

- + From a binary patient representation {X} derive a latent patient representation {Z}.
- + Once the general representation is obtained mapping it for the different medical targets.



11

Unsupervised Stacked Denoising Autoencoder Network



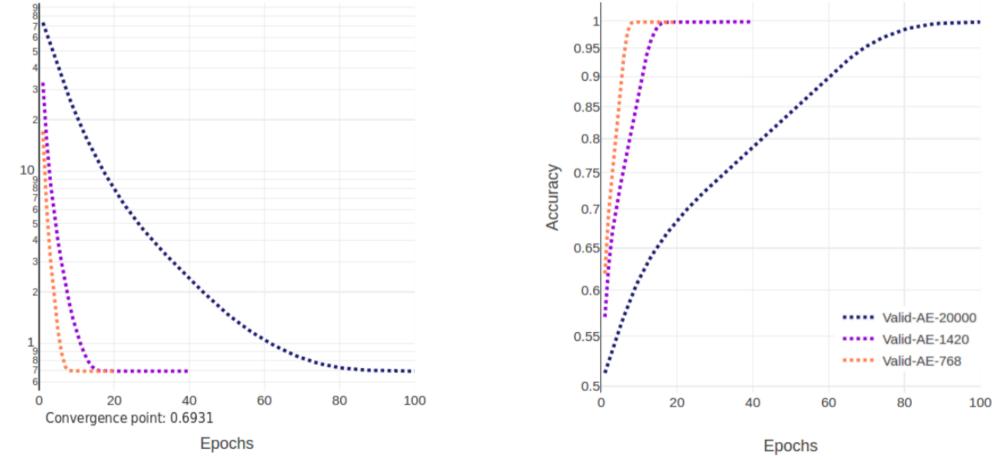
Experiment Analysis

1) Number of Gradient Updates as Factor to Early Model Convergence.

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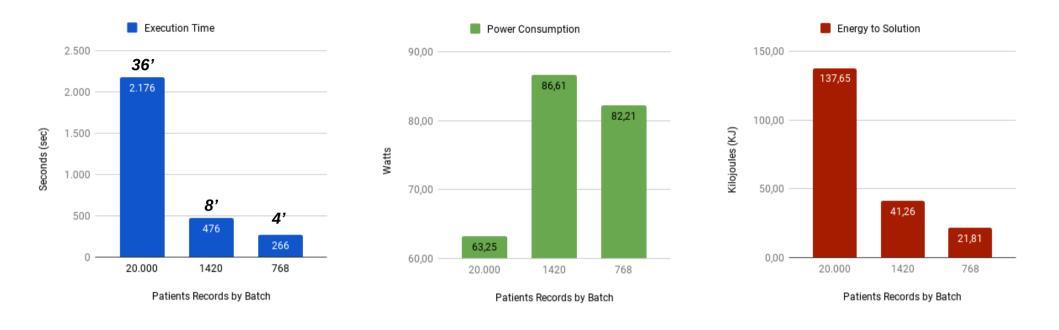
	1-Layer1	2-Layer2	3-Layer3	4-Activation_funct	5-GD_Optimizer	6-Learning_rate	7-Dropout-rate
0	2048	2048	768	relu	adam	0.0001	0.5

Network convergence using batch partitions of [20000, 1420, 768] records to generate [4, 59, 110] gradient updates by epoch respectively.

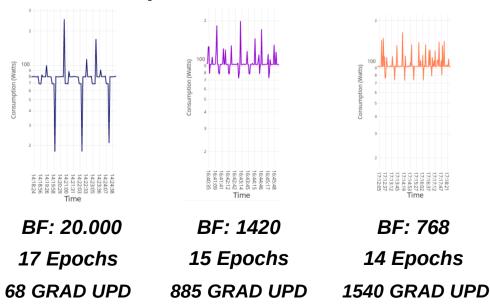


Loss

Number of Gradient Updates Impact the Energy to Solution



Power consumption in a window of 6 minutes

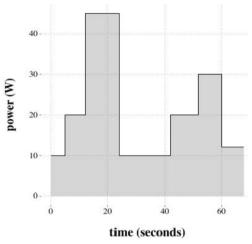


Energy Monitoring tool for Workload Characterization

Energy Consumption Metrics

1) Discretization of Energy Consumption per Time-Unit:

$$Energy = \int Power(t) dt$$
$$Energy = \sum_{i=1}^{N} Power(i) * \Delta t(i)$$



2) Energy to Solution (E2S):

$$E2S = \sum_{i=1}^{N} Power_{Node}(i) * max \ (\Delta t_{CPU}(i), \Delta t_{GPU}(i))$$

3) Instantaneous Power Consumption per Node:

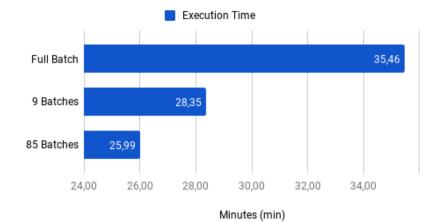
$$Power_{Node}(i) = \sum_{j=1}^{nc} P_{CPU}^{j}(i) + \sum_{j=1}^{ng} P_{GPU}^{j}(i) + \sum_{j=1}^{nm} P_{RAM}^{j}(i)$$

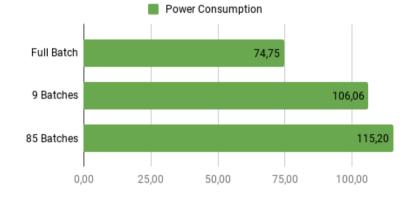
5. Source enerGyPU and enerGyPhi Monitor for Power Consumption and Performance Evaluation on Nvidia Tesla GPU and Intel Xeon Phi. By GARCÍA H. John et al. 2016

Analysis of Energy Efficiency for Training the USDA on 1-GPU

S-1: Full Batch with 84.999 Patients Records





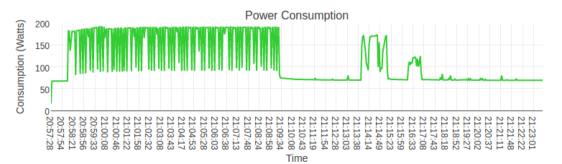


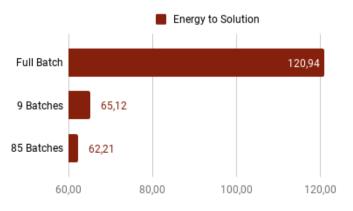
Watts

S-2: 9 Batches that Contain 10.000 Patients Records



S-3: 85 Batches that Contain 1000 Patients Records

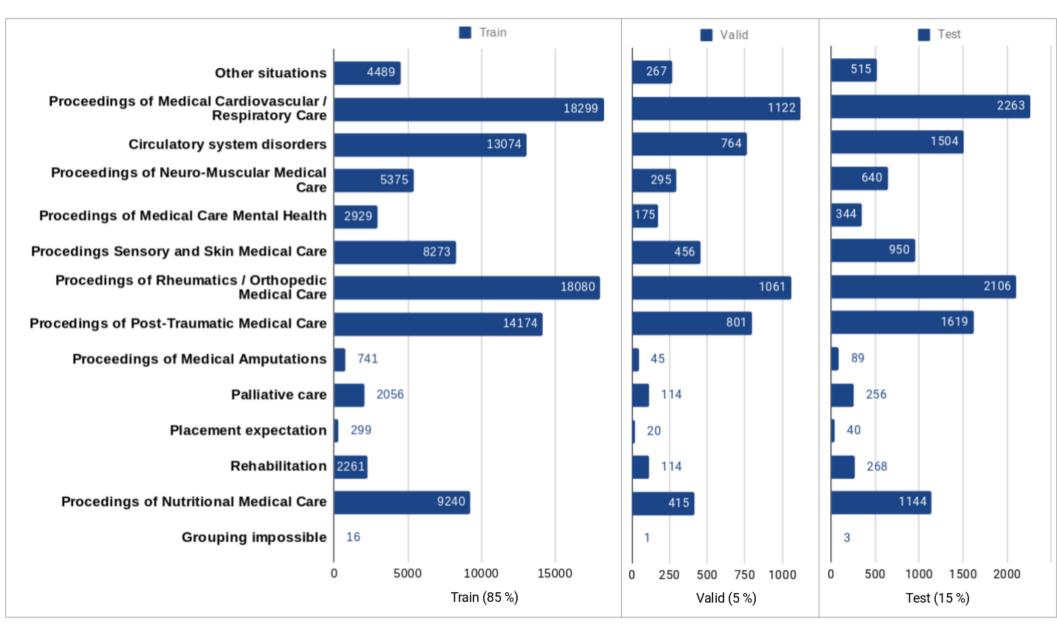




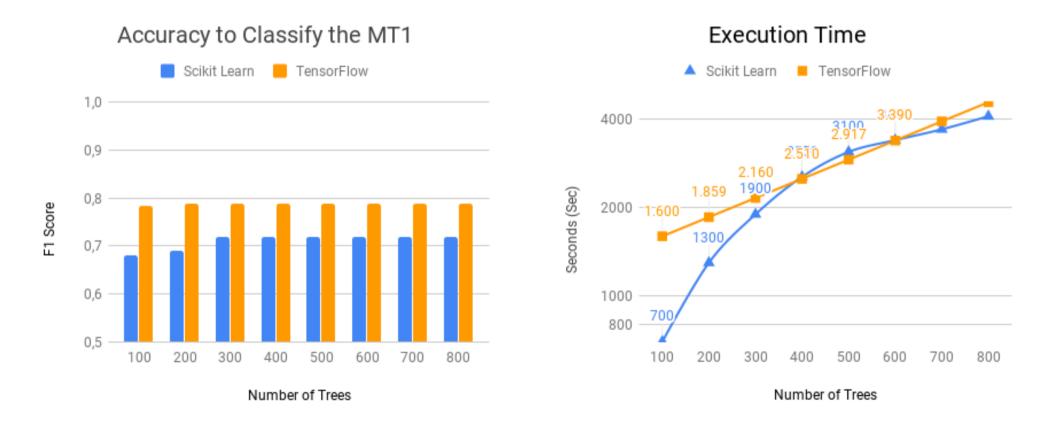
KiloJules (KJ)

Supervised Learning Medical Target 1

Medical Target 1: Care Purpose Description Labels at ICU



Supervised Learning Random Forest Classifier

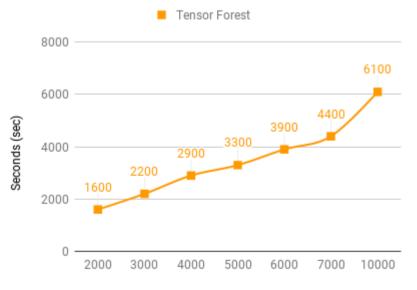


Experiments: Tensor Forest Analysis on Different Number of Features

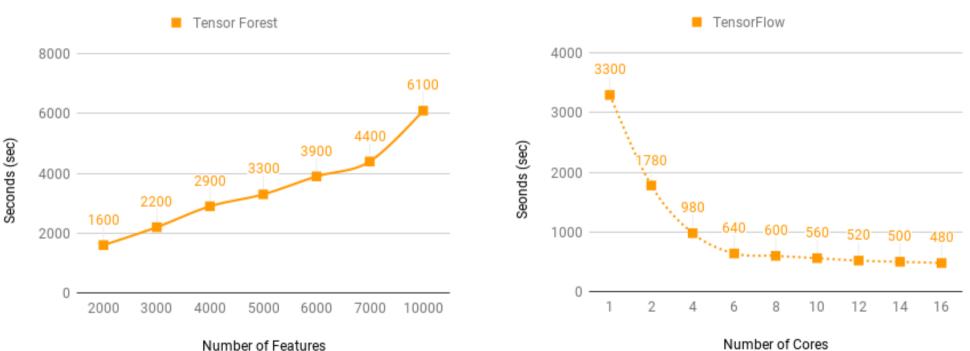


Accuracy to Classify the MT1

Execution Time on Single-core Processor



Number of Features

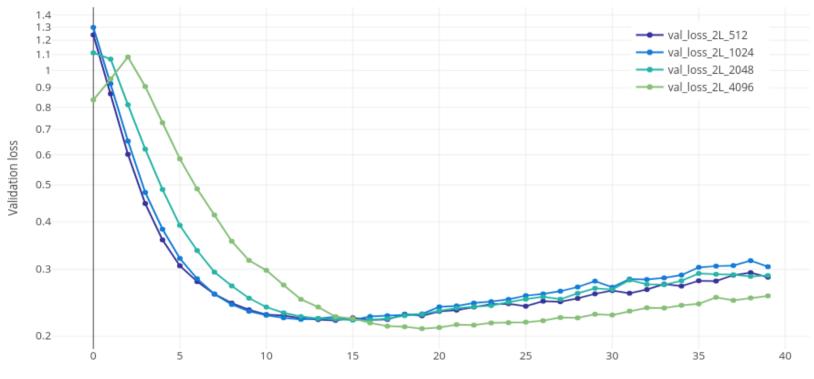


Execution Time on Multi-core Processor

Execution Time on Single-core Processor

Supervised Learning Feed-forward Multilayer Perceptron

Experiments: Feed-forward Multilayer Perceptron



Epoch

Stretching the 4096 Neurones over Deep Architectures

Number of units $= 4096$	F1 score	execution time	power consumption	energy consumption
		(hours)	(watts)	Mj
2 layers - 4096 units	0.92	4.85	214.86	3.75
4 layers - 2048 units	0.85	4.8	173.17	32.99
8 layers - 1024 units	0.72	4.76	153.43	2.68
16 layers - 512 units	0.75	4.72	130.95	2.23

26

Preliminary Results: F1-score for Different Stretching Configurations



Architecture	F1 score	execution time	power consumption	energy consumption
		(hours)	(watts)	Mj
256 units - 2 layers - 128 units	0.91	4.71	92.27	1.57
2048 units - 8 layers - 256 units	0.91	4.73	101.68	1.73
8192 - 2 layers - 4096 units	0.92	4.85	214.86	3.75

Distributed Processing for Training DNN on Jetson TX2 Mini-Clusters

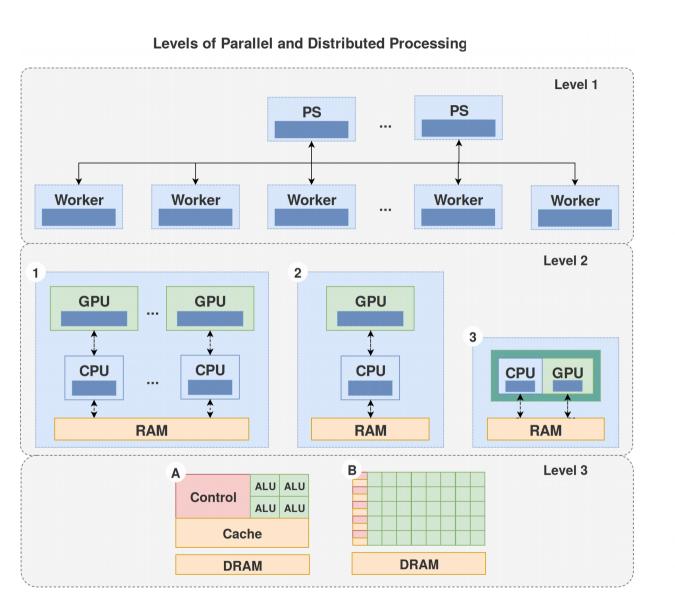
Computational Resources



Mini-Cluster Jetson TX2



Array Node with 24 Jetson TX2

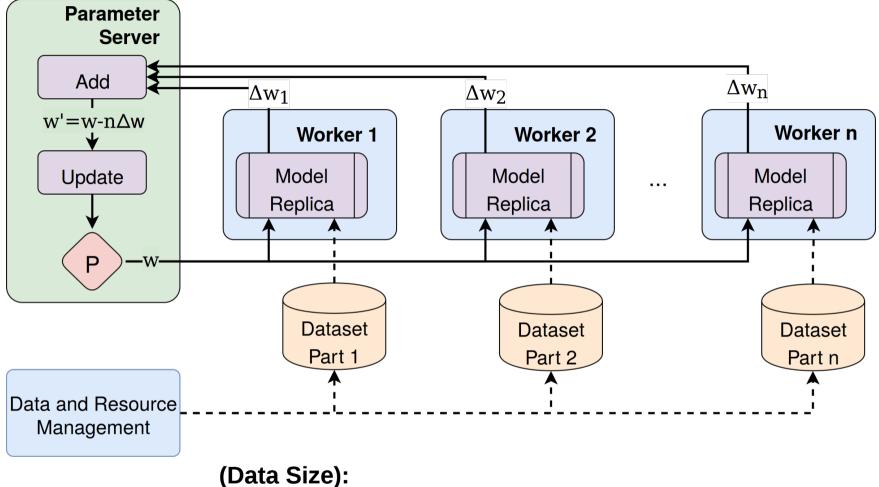




Cross	-platf	orm Libr	ary			
User Interface	alysis Interface					
DiagnoseNET DNN I	DiagnoseNET DNN Models Diagnos					
DiagnoseNET Par & Distributed Trai			anagement & rce Manager			
Training Libraries	Infe	erence Libs				
Python Client	С	++ Client				
C	API					
Distributed Master	Distributed Master Dataflow executor					
Network	ing La	yer	enerGyPU			
GRPC	МА	Monitor-Tool				
Kernel Impl cul						
Relu	v2	MatMul				
GCC, CUDA, Protobuf, Bazel,						

7. Adapted from Snap Machine Learning. By IBM Research et al. 2018 8. Adapted from TensorFlow Architecture. By Google Research.

Task-Based Data Parallelism: Synchronous

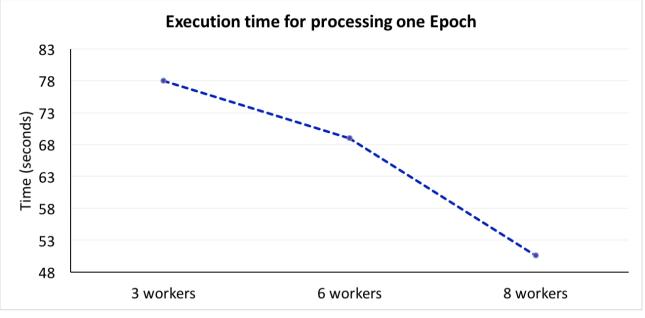


- + Setting the number of workers and micro batch.
- + Fine-tuning DNN hyperparameters.
- + Speeds up the training.
- + I/O Intensive.

9. Adapted from TensorFlow: Large-Scale Machine Learning on Heterogeneous Distributed Systems. By Google Research. 2015.

Preliminary Results to Scale the Unsupervised Representation Learning

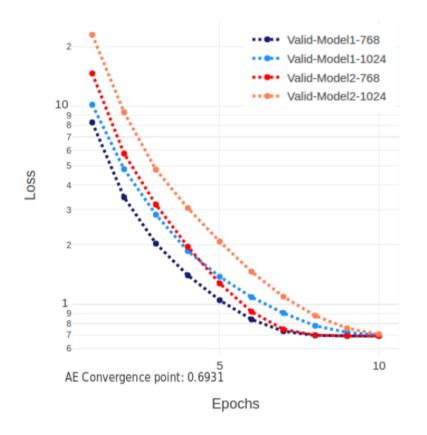
Preliminary results using: 10.000 records and 11.466 features.



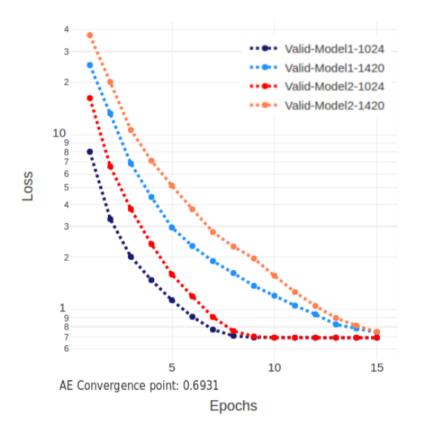


Number of Workers and Task Granularity as Factor to Early Model Convergence

 Early convergence comparison between different groups of workers and task granularity for distributed training with 10.000 records and 11.466 features.



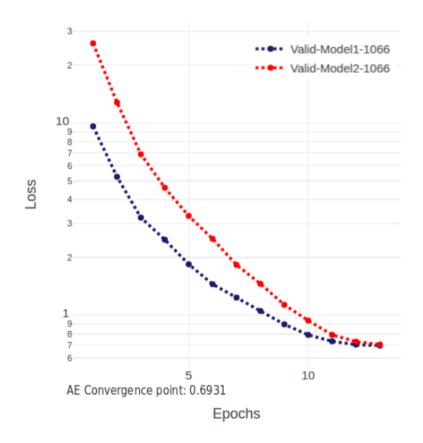
1.30 mins in avergange for processing one epoch on 1 PS 3 workers.



1 min in avergange for processing one epoch on 1 PS 6 workers.

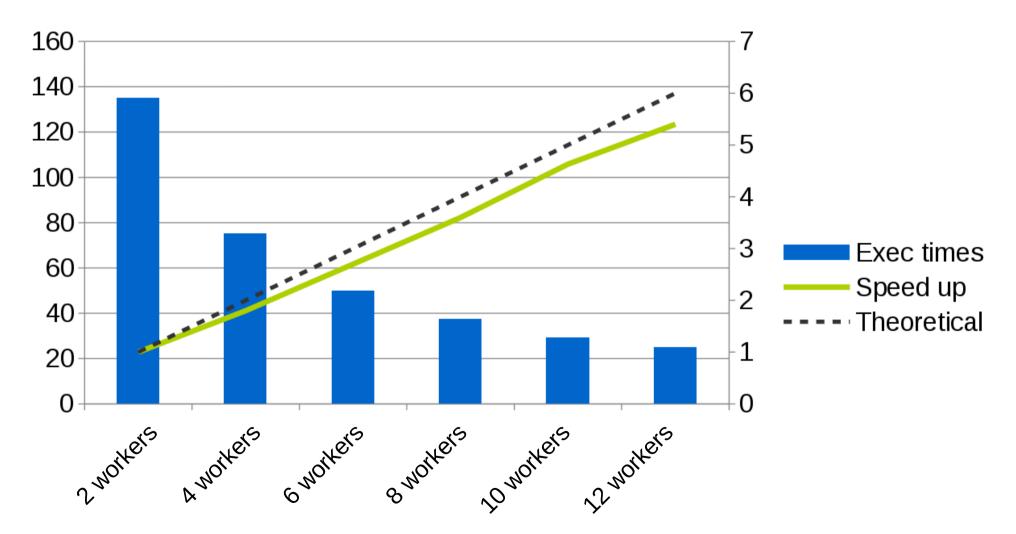
Number of Workers and Task Granularity as Factor to Early Model Convergence

 Early convergence comparison between different groups of workers and task granularity for distributed training with 10.000 records and 11.466 features.



50.6 secs in avergange for processing one epoch on 1 PS 8 workers.

8-Layers Model with 256 Neurons per Layer on a Cluster with 2, 4, 6, 8, 10 and 12 Jetsons TX2



Conclusions

Using hundreds of **Gradient Updates by Epochs** with synchronous data parallelism offer an efficient distributed DNN training to early convergence.

Adapting the **Number of Records by Batch** or the **Model dimensionality** to minimize the bottleneck of data transfer from host memory to device memory reducing the GPU idle status.

Use a mini-Cluster of Jetson TX2 presents good results in distributed training using synchronous data parallelism.

Therefore, this can be used as a learning center with minimal infrastructure requirements and low power consumption and brings the opportunity to use a dataset with more patient's features.

Latent Representation:

- Reduces the number of sparse features without loss of precision in future classification.
- Reduces training time (41 %) to classify the first medical target.

Next Work on DiagnoseNET

- Distributed others kind of DNN architectures Like (CNN, RNN) and Tensor Forest.
- Compare several architecture:
 - multi-GPU (share memory)
 - vs Cluster (distributed memory)
 - vs Array (hybrid memory)
- For several medical task:

MT-1: Predict the '*Care Purpose or Major Clinical Category*' of patients in (coarse grain CMC / fine grain GHJ) from inpatients features recorded at the admission time.

MT-2: Predict the '*Clinical Procedures*' from Inpatients features recorded at the admission time and the Primary Morbidity.

MT-3: Predict the '*Inpatient Destination*' (home, transfer, death) and length of hospitalization stay from inpatients features recorded at the admission time and Primary Morbidity and Clinical Procedures.

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